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1440-131

A standard linear barcode is positioned vertically on the left side of the page. To its right, there is a vertical column of numbers and symbols: '08', a diagonal line, '871029', a diagonal line, and '10'. The barcode itself is composed of vertical black lines of varying widths on a white background.

Docket No. D9310

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

TRANSMITTAL LETTER

Certification Under 37 C.F.R. § 1.10 (if applicable)

EH455864259US

June 9, 1997

"Express Mail" Mailing Number

Date of Deposit

I hereby certify that this application is being deposited with the United States Postal Service "Express Mail Post Office to Addressee" service under 37 C.F.R. § 1.10 on the date indicated above and is addressed to the Commissioner of Patents and Trademarks, Washington, D. C. 20231.

RICHARD TAYLOR
(Typed or Printed Name of
Mailing Person)

(Signature of Person
Mailing Application)

Anticipated Classification of Prior Application:

Anticipated Classification of This Application:

Examiner _____
Class 073 Subclass _____
Art Unit 2212

Examiner _____
Class 073 Subclass _____
Art Unit 2212

Commissioner of Patents & Trademarks
Box FWC
Washington, D. C. 20231

Sir:

This is a request for filing a

Continuation) Application under 37 C.F.R. § 1.60 of pending
____ Continuation-) prior Application Serial No. 08/679,332
) filed July 11, 1996 which is a continuation of Application
) Serial No. 08/416,100 filed April 4, 1995 (now U. S. Patent
) 5,560,244) which is a continuation of Application Serial No.
) 08/107,017 filed August 17, 1993 (now U. S. Patent 5,463,897),
) for SCANNING STYLUS ATOMIC FORCE MICROSCOPE WITH
) CANTILEVER TRACKING AND OPTICAL ACCESS" by Craig B. Prater,
) James Massie, David A. Grigg and Virgil B. Elings.

The filing fee (for large entity) is calculated below:

CLAIMS AS FILED IN THE PRIOR APPLICATION, LESS
ANY CLAIMS CANCELED BY AMENDMENT BELOW

FOR:

Basic Fee		\$770.00	
Total Claims	<u>36</u> -20 = <u>16</u>	x \$ 22.00	\$ <u>352.00</u>
Independent Claims	<u>7</u> - 3 = <u>4</u>	x \$ 80.00	\$ <u>320.00</u>
Multiple Dependent Claims	—	\$260.00	\$ <u>-0-</u>
TOTAL FILING FEE			\$ <u>1440.00</u>
Assignment Recording Fee		\$ 40.00	\$ <u>-0-</u>
		TOTAL FEES	\$ <u>1,440.00</u>

The Commissioner is hereby authorized to charge any fees which may be required or to credit any overpayment to Deposit Account No. 02-3823. A duplicate copy of this letter is enclosed for charge purposes.

A check in the amount of **\$1,440.00**, is enclosed to pay the filing fee for the above-identified patent application.

A Preliminary Amendment is enclosed.

Please cancel claims 1-41 of the prior application.

Amend the specification by inserting before the first line the sentence: --This application is a continuation of pending prior Application Serial No. 08/679,332 filed July 11, 1996 which is a continuation of Application Serial No. 08/416,100 filed April 4, 1995 (now U. S. Patent 5,560,244) which is a continuation of Application Serial No. 08/107,017 filed August 17, 1993 (now U. S. Patent 5,463,897), for "SCANNING STYLUS ATOMIC FORCE MICROSCOPE WITH CANTILEVER TRACKING AND OPTICAL ACCESS" by Craig B. Prater, James Massie, David A. Grigg and Virgil B. Elings.--

Enclosed is a copy of the inventor-signed, pending prior Application Serial No. 08/679,332 including a copy of the oath or declaration showing the original signature or an indication it was signed. I hereby verify that the papers are a true copy of the latest signed prior Application Serial No. 08/679,332, and further that all statements made herein of my own knowledge are true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issuing thereon.

The prior application has been assigned to DIGITAL INSTRUMENTS, INC. and to THE REGENTS OF THE UNIVERSITY OF CALIFORNIA. Said assignment has been duly recorded in the U. S. Patent & Trademark Office.

The power of attorney in the prior application has been revoked and has been granted to **Patrick F. Bright, Reg. No. 24,318**. A Power of Attorney, duly executed by applicant, has previously been submitted. (copy enclosed)

Address all future communications to:

Patrick F. Bright, Esq.
BRIGHT & LORIG, P.C.
633 West Fifth Street, Suite 3330
Los Angeles, California 90071
(213) 627-7774

June 9, 1997

Patrick Bright

Patrick F. Bright
Reg. No. 24,318
Attorney of Record

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re application of:) **Attorney Docket: D9310**
CRAIG B. PRATER ET AL.)
Serial No.: UNKNOWN)
(Continuation of 08/679,332))
Filed: JUNE 11, 1997)
Group Art No: 2212)
Examiner: UNKNOWN)
For: SCANNING STYLUS ATOMIC FORCE)
MICROSCOPE WITH CANTILEVER)
TRACKING AND OPTICAL ACCESS)

PRELIMINARY AMENDMENT

Honorable Commissioner of Patents
and Trademarks
Washington, D.C. 20231

Sir:

Before acting on the above-identified application for the first time, please
amend the application as follows:

IN THE TITLE

Please change the title of this application to --SCANNING STYLUS ATOMIC
FORCE MICROSCOPE WITH CANTILEVER TRACKING AND OPTICAL ACCESS--.

IN THE SPECIFICATION

In the amendment filed with the present continuation application in which continuation data was inserted before the first line of page 1 of the specification, after "April 4, 1995", please insert --now U. S. Patent No. 5,560,244--, and after "August 17, 1993" insert --now U. S. Patent No. 5,463,897--.

Page 2, line 17, before "entitled" insert --now U. S. Patent No. 5,412,980--.

Page 2, line 23, change "53(12), Sep. 19, 1988)" to --65, 1 January 1989--.

Page 4, line 13, change "Mayer" to --Meyer--;

Page 4, line 15, change "1989" to --1991--.

Page 9, line 23, after "08/009,076" insert --now U. S. Patent No. 5,266,801--.

Page 14, line 23, change "4" to --4A--.

Page 16, line 5, change "4" to --4A--.

Page 16, line 23, change "4" to --4A--.

Page 18, line 7, after "beam" insert --47--; same line, change "47" to --48--.

Page 22, lines 15 and 17, change "44" to --68--.

Page 25, line 22, after "beam" insert --91--.

Page 26, line 9, after "motion." insert --the beam 92 reflected from

cantilever 14 is detected by position sensitive detector 16.--

Page 29, line 18, after "source" insert --100--.

Page 31, line 22, change "4" to --4A--.

Page 32, line 6, change "4" to --4A--.

Page 32, line 7, change "48" to --42 (Fig. 4B)--.

Page 33, line 9, delete "the" (the second occurrence);

Page 33, line 20, after "08/009,076" insert --now U. S. Patent No. 5,266,801--.

IN THE CLAIMS

Please cancel claims 1-41.

Please add the following new claims 42-77 as follows:

--42. An atomic force microscope including an optical lever system, comprising:

 a scanning mechanism;

 an optical lever system including a light source not moved by said scanning mechanism;

 a cantilever moved by said scanning mechanism so that said cantilever may be scanned over a sample;

 a position detector not moved by said scanning mechanism which

receives reflected light from said cantilever and detects an angular deflection of a free end of said cantilever; and

said atomic force microscope further comprising an optical assembly including at least one steering lens to guide light emitted from said light source onto said cantilever to follow substantially a fixed position on said cantilever during movement of said scanning mechanism.--

--43. The atomic force microscope as recited in claim 42, wherein light reflected to said position detector does not pass through said steering lens.--

--44. An atomic force microscope as recited in claim 43, wherein said position detector is located substantially at a point where light beams reflected from said cantilever converge when said cantilever is undeflected during a full extent of movement of said scanning mechanism so that said position detector is substantially sensitive to a deflection motion of said cantilever rather than a scanning motion of said cantilever.--

--45. An atomic force microscope as recited in claim 42, wherein a stylus is included substantially on the free end of said cantilever.--

--46. An atomic force microscope as recited in claim 42, wherein said scanning mechanism comprises a piezoelectric tube.--

--47. An atomic force microscope as recited in claim 46, wherein said steering lens is included in said piezoelectric tube.--

--48. A method of operating an atomic force microscope having an optical lever system with a light source, a cantilever and a position detector, and further having a steering lens assembly attached to a steering mechanism, the method comprising the steps of:

generating light;

directing said light onto said cantilever using said steering lens assembly so that said light strikes a substantially fixed position on said cantilever during a movement of said scanning mechanism; and

receiving a reflected light reflected from said cantilever using said position detector to detect an angular bending of said cantilever.--

--49. A method as recited in claim 48, further comprising the steps of:

splitting said light into a first beam which strikes said cantilever and a second beam which is directed to a second position detector.--

--50. A scanning force microscope device comprising in combination:

- a. a sensing probe having a substantially reflective surface on one side and a scanning tip on the opposite side, said tip adapted to be positioned adjacent a surface to be scanned;
- b. illuminating means for generating a radiant energy beam and for applying said beam to said reflective surface;
- c. position control means coupled to said sensing probe for moving

said scanning tip substantially parallel to a surface to be scanned in a predetermined pattern and for moving said scanning tip orthogonal to the surface to follow the contours of the surface;

 d. beam positioning means for directing said radiant energy beam to follow said sensing probe through lateral motion of said probe; and

 e. detector means adapted to receive the energy beam reflected from said reflective surface and operable in response to movement of said reflected energy beam corresponding to position changes to said sensing probe relative to the surface to be scanned to produce a motion representing signal corresponding to tip movement following the contours of the scanned surface, whereby tip motion in a direction orthogonal to scanning motion results in a series of electrical signals corresponding to and representative of the surface contours of the scanned surface.--

--51. In a scanning force microscope having a sensing lever having a tip mounted for movement in response to relative vertical distance changes between the tip and a sample surface as the tip moves laterally with respect to the sample

surface, apparatus for sensing the vertical movement of the tip relative to the surface being scanned and for creating a signal representative of such vertical movement comprising:

- a. a reflective surface carried by the sensing lever;
- b. an energy source positionally decoupled from lateral movement of the sensing lever for emitting a radiant energy beam including focussing means for applying said beam to said reflective surface;
- c. control means for moving the sensing lever and tip laterally over the surface of a sample to be scanned including beam directing means for causing said radiant energy beam to follow the lateral motion of the sensing lever;
- d. driving means for moving the sensing lever and tip in a vertical direction towards and away from the surface of the sample to be examined; and
- e. detection means positioned to receive said energy beam after reflection from said reflective surface for signalling changes in the beam position, said changes corresponding to and being representative of vertical displacement of the sensing lever tip during lateral motion over the sample surface.--

--52 The scanning force microscope of claim 51, further including means for creating an image of the lever in space at a point in space such that said image does not appear to move when the lever is moved laterally.--

--53. The scanning force microscope of claim 51 further including a lens system attached to a deformable ceramic transducer having an axis to create an image of the lever substantially at a selected point along the axis of said transducer at which the lever image appears to be stationary, notwithstanding lateral movement of the lever.--

--54. The scanning force microscope of claim 51 wherein said detection means are isolated from and independent of lever tip movement, said detection means being responsive to the light beam reflected from said reflective surface for signalling changes in light beam position resulting from bending movement of the sensing lever, whereby detection means output signals correspond to and are representative of the vertical motion of the sensing lever tip and represent the contours of a scanned surface.--

--55. The scanning force microscope of claim 51 wherein detection means output signals are processed to produce control signals which correspond to and are representative of the contours of a scanned surface.--

--56. In a scanning force microscope having a lever with a reflecting surface and a sensing tip wherein the sensing tip is responsive to forces resulting from the

proximity of the sensing tip to a sample surface under investigation, apparatus for sensing the response of the tip to the forces comprising:

- a. a light beam source for generating a light beam, said source being mounted to permit relative lateral motion between said source and the lever during scanning;
- b. a light beam steering device for laterally steering said light beam to follow the reflective surface of said lever as said lever moves relative to said light beam source;
- c. a motion control device for creating relative motion between said sensing tip and said sample surface; and
- d. a detection device for detecting light reflected from said lever.--

--57. The microscope of claim 56 wherein the light beam source is a laser.--

--58. The microscope of claim 56 further including at least one lens interposed between the light beam source and said reflective surface wherein said beam steering device comprises a free end and a fixed end, said free end being coupled to said lens.--

--59. The microscope of claim 56 further including at least one mirror interposed between the light beam source and said reflective surface wherein the beam steering device comprises a free end and a fixed end, said free end being coupled to said mirror.--

--60. The microscope of claim 56 wherein said motion control device includes a piezo-electric device having a free end and a fixed end, said free end of said motion control device being adapted to provide relative scanning motion between said tip and the sample surface under investigation.--

--61. The microscope of claim 56 wherein said detection device is an array of at least two photodiodes.--

--62. The microscope of claim 56 wherein the sensing tip is in contact with the sample surface under investigation.--

--63. The microscope of claim 56 wherein said detection device is adapted to create an error signal which can be used in conjunction with applied position signals to create a three dimensional map of said sample surface.--

--64. The microscope of claim 56 wherein said detection device generates an error signal which is processed to create a control signal to be used in conjunction with applied position signals to create a three dimensional map of the sample surface.--

--65. The microscope of claim 56 wherein said light beam steering device is integral with said motion control device.--

--66. In a scanning force microscope having a lever with a reflecting surface and a sensing tip wherein the sensing tip is responsive to forces resulting from the proximity of the sensing to a sample surface under investigation, apparatus for

sensing the response of the tip to the forces comprising:

- a. a light beam source for generating a light beam;
- b. a motion control device for creating relative motion between the sensing tip and the sample surface, said motion control device having a fixed end and a free end, said free end being adapted to provide relative scanning motion between the scanning tip and the sample surface;
- c. at least one lens interposed in said beam of light between said source and the reflecting surface, said lens fixed to the frame of reference of said free end of said motion control device such that said lens causes said beam to track laterally the motion of said reflecting surface; and
- d. a detection device for detecting light reflected from the reflecting surface.--

--67. The microscope of claim 66 wherein said light beam source is a laser.--

--68. The microscope of claim 66 wherein said detection device is an array of at least two photodiodes.--

--69. The microscope of claim 66 wherein the sensing tip is in contact with the sample surface under investigation.--

--70. The microscope of claim 66 wherein said detection device is adapted to create an error signal which can be used with applied position signals to create a three dimensional map of the sample surface.--

--71. The microscope of claim 66 wherein said detector generates a signal which is processed to create a control signal to servo said motion control device, wherein said control signal is further used in conjunction with applied position signals to create a three dimensional map of the sample surface.--

--72. The microscope of claim 66 further including at least one mirror interposed between the light beam source and said reflective surface wherein the beam steering device comprises a free end and a fixed end, said free end being coupled to said mirror.--

--73. The microscope of claim 66 wherein at least said one lens is fixed to the frame of reference of the free end of said motion control device.--

--74. The method of operating a scanning force microscope having a probe with a lever having a reflecting surface and a sensing tip responsive to forces resulting from the proximity of the tip to a sample surface under investigation wherein said probe is scanned across a surface, and wherein the scanning force microscope further has a light beam source for generating a light beam wherein the light beam source does not move with the scanning probe during scanning, the

method comprising the steps of:

- a. steering the light beam to follow the motion of the sensing probe;
- b. reflecting the light beam from the reflecting surface; and
- c. detecting the light beam reflected from the moving probe with a detector.--

--75. The microscope of claim 74 including the further step of bringing the sensing tip into contact with the surface of the sample---

--76. The microscope of claim 74 including the further step of processing the signal generated from the detection of the reflected beam, to generate a control signal which is transmitted to a translation device which causes said sensing tip to move.

--77. The microscope of claim 74 including the further step of generating an image from the control signal.

IN THE ABSTRACT

Page 44, line 5, delete "a"; same line, delete "beam";

Page 44, line 6, change "laser" to --light--; same line, change "said" to --a--;

Page 44, line 7, change "laser" to --light--;

Page 44, line 9, change "laser" to --light--;

REMARKS

In this Preliminary Amendment, applicant presents for examination on the merits in the first Office Action claims 42-49 which correspond to claims 42-45, 48, 49, 57 and 58 from the parent of this application, namely U. S. Patent Application Serial No. 08/679,332 filed in the PTO on July 11, 1996. The PTO had rejected these claims on the ground of obviousness-type double patenting. Enclosed is a Terminal Disclaimer that overcomes this rejection.

Claims 50-77 presented in this Preliminary Amendment were copied from Harp et al. U. S. Patent 5,524,479 (the "'479 patent"), issued June 11, 1996 (copy attached as EXHIBIT A). Under the provisions of 37 C.F.R. § 1.608, applicant respectfully requests the PTO to declare an interference between the claims presented herein and the corresponding claims in the attached '479 patent. EXHIBIT B hereto shows that applicant has an adequate written description, within the meaning of 35 U.S.C. § 112, to support claims 50-77. These claims 50-77 are identical to the corresponding claims of the '479 patent. See EXHIBIT C hereto. Since this application is descended from applicant's U. S. Patent Application Serial No. 101,017 filed in the PTO on August 17, 1993, and since the specification and drawings of this application are identical to the specification and drawings of the '017 application, applicant should be named senior party in any such interference.

Applicants request entry and allowance of claims 42-77. Under 37 C.F.R.

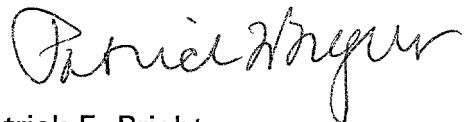
Serial No.: UNKNOWN (Continuation of 08/679,332)
Applicants: C. PRATER et al.

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§ 1.607, applicants also request the PTO to declare an interference between claims 50-77 of this application and the corresponding claims of the '479 patent. See EXHIBITS B and C, as called for by Rule 607(a).

The Commissioner is authorized to charge Deposit Account No. 02-3823 for any fee or cost incurred by submission of this Preliminary Amendment. A copy of this document is attached for this purpose.

Respectfully submitted,



Patrick F. Bright
Reg. No. 24,318
BRIGHT & LORIG, P. C.
633 West Fifth Street, #3330
Los Angeles, CA 90071
(213) 627-7774

June 9, 1997



06/09/97

TITLE OF THE INVENTION

ATOMIC FORCE MICROSCOPE AND METHOD OF OPERATING AN ATOMIC
FORCE MICROSCOPE

BACKGROUND OF THE INVENTION

Field of the Invention

The present invention relates to scanned-stylus atomic force microscopes and a method of operating a scanned-stylus atomic force microscope, and in particular to large scan optical lever atomic force microscopes.

Discussion of the Background

Atomic force microscopes (AFMs) are extremely high resolution surface measuring instruments. The AFM is described in detail in several U.S. Patents including 4,935,634 to Hansma et al., 5,025,658 to Elings et al., and 5,144,833 to Amer et al. The AFM scans a stylus mounted on a flexible spring lever (cantilever) with respect to a sample. The actual motion can be produced by translating either the sample or the stylus and cantilever. This motion can be produced by any scanning mechanism, but is typically produced by a piezoelectric translator. All generic scanning mechanisms will be referred to as scanners.

Surface features on the sample interact with the stylus and cause the cantilever to deflect. By measuring the deflection of the cantilever as a function of position over

the surface, a map of the surface can be created. In practice, it is often necessary to minimize the force that the cantilever applies to the surface. For this reason, AFMs are usually run under feedback in the "constant force mode." In this mode, the cantilever deflection is kept constant during imaging by moving either the cantilever or the sample with respect to each other. The sample surface is then mapped out by reading a signal indicating the relative motion of the cantilever or sample needed to keep the cantilever deflection constant. When a feedback system is used to keep the cantilever deflection constant, this deflection (and hence force on the sample surface) can be held at a minimum value.

There are also a variety of AC modes where the cantilever is vibrated and features of the sample are sensed by measuring the amplitude, phase, or frequency of the vibrating cantilever. See for example copending Application serial no. 07/926,175 entitled An Ultra Low Force Atomic Force Microscope by Elings and Gorley.

The first atomic force microscopes used the principal of electron tunneling to detect minute deflections of the cantilever. More recently, two groups (Meyer and Amer, Appl. Phys. Lett., 53 (24), Dec. 12 1988 and Alexander et al, Appl. Phys. Lett., 53(12), Sep. 19, 1988) independently succeeded in using the "optical lever technique" to measure cantilever deflections with subnanometer resolution. The "optical lever" technique works in the following way.

Referring to Fig. 1, a prior art AFM system is illustrated. An AFM cantilever 14 is made so that it is sufficiently reflective that it can act as at least a partial mirror. A laser beam 17 from a laser 10 is focused onto one side of the AFM cantilever 14 having a stylus 15 mounted thereon. Laser beam 14 passes through or alongside a scanner 12 using lens 11 and the reflected beam 18 is directed to a position sensitive detector 16, usually a multi-segment photodiode. Cantilever 14 is attached to a mounting substrate 20, which is attached to scanner 12, or to an optional mounting element 19. A cantilever deflection changes the angle of the cantilever with respect to the incoming laser beam 17 and thus moves the reflected laser beam 18 on the position sensitive detector 16 as the cantilever 14 is scanned over the sample 13.

Prior art scanned-stylus AFMs as shown in Fig. 1 focus a laser spot onto one side of a cantilever and then the scanner moves the cantilever over the sample. Since the cantilevers are typically a few hundred microns long and a few tens of microns wide, the focused laser spot must be only 10-30 microns in diameter so that laser light does not spill around the cantilever and onto the sample. If laser light spills around the cantilever, the AFM's sensitivity and therefore vertical resolution is decreased. Also the position sensing photodiode may be disturbed by optical interference from the sample. This means that if a prior art scanned-stylus AFM

scans the cantilever more than 10-30 microns, the cantilever will move out from under a stationary laser beam, and the AFM's performance will deteriorate. There is great interest in scanned-stylus AFMs that can scan in the range of 100 microns, much larger than the range of this prior art AFM.

The majority of AFMs that have been built scan a small sample under a fixed stylus and cantilever. There is, however, great interest in AFMs that scan the stylus over a fixed sample. This method has a number of advantages, including the ability to image samples that are too large to be scanned easily. A number of scanned-stylus AFMs have been built and described in the literature. For example, such instruments have been built by G. Mayer and N.M. Amer, *Appl. Phys. Lett.*, 56, p. 2100 (1990), C.B. Prater et al., *J. Vac. Sci. Technol.*, B9, p. 989 (1989), Hipp et al, *Ultramicroscopy* 42-44, p. 1498 (1992), Putman et al, presented at the OE/LASE '93 Conference, January 19, 1993, Los Angeles, CA, Baselt and Baldeschweiler *Rev. Sci. Instrum.* 64, p.908 (1993), Clark and Baldeschweiler *Rev. Sci. Instrum.* 64, p. 904, (1993), and by Digital Instruments, U.S. Patent 5,025,658 (E.g., *Stand Alone™ AFM, Large Sample Scanning Probe Microscope*) assigned to the assignee of the present application.

All of the previous instruments suffer from compromises that do not allow them to take full advantage of the capabilities of AFMs that scan by moving the samples instead of the stylus. Prior art scanned-stylus AFMs that use a fixed

laser to measure cantilever deflection have a maximum scan size set by the diameter of the laser beam at the cantilever. If the cantilever is scanned a distance larger than the beam size, it will move out from under the beam, and it will no longer be possible to detect the cantilever motion.

A small number of optical lever scanned-stylus microscopes have been built by using a laser beam that is defocused so that in the plane of the cantilever, it is larger than the desired scan range of the cantilever. Microscopes of this type have been built separately by Meyer et al, *supra*, C. B. Prater et al. *supra*, Hipp et al, *supra*, Baselt et al, *supra*, and Clark et al, *supra* and are typically of the type shown in Fig. 1. The performance of this type of scanned-stylus AFM is greatly diminished at scan ranges of larger than 10-20 microns. This performance loss is seen in the form of images that appear "warped" and uncontrolled force variation across the scan field. These effects have been recently described by Baselt et al, *supra*.

The reason for this performance loss is as follows. Scanned-stylus AFMs often use a piezoelectric tube translator (12 in Fig. 1) to scan the cantilever over the sample. Typically, one end of the scanner is held fixed and the other end performs the scanning pattern with a pendulum-like motion. This means that scanning the cantilever over the sample surface changes both the angle and position of the cantilever with respect to the incoming laser beam and the angle and

position of the cantilever with respect to the position sensitive detector. Some of these problems are described in the paper by Hipp et al, *supra*. In addition, some commercial cantilevers are not flat, but are instead warped by a small amount. Even in the case that the cantilever motion is small enough that the laser stays on the cantilever, the deflection of the reflected beam can change by large angles as the laser moves on this warped surface. For example Baselt et al, *supra*, measured false cantilever deflections of 45 nm while scanning a warped cantilever only 750 nm under a fixed laser.

The net result of these angular and position changes is to move the reflected laser beam across the position sensitive detector. In "constant force mode" operation, however, the position of the laser beam on the detector is held constant with a feedback loop that moves the cantilever with respect to the sample. So changes in the relative angles and positions of the laser, cantilever, and detector will cause the feedback loop to exert more or less force on the surface as the cantilever is scanned to keep the position of the laser constant on the detector. These force variations can be very destructive. Many biological samples cannot be imaged with forces larger than one nanoNewton (nN). See for example Hoh and Hansma, *Trends in Cell Biology*, 2, p. 208 (1992). In the above case, where a warped cantilever caused a false deflection of 45 nm over a 750 nm scan, the force variation could be as high as 1-10 nN for typical cantilevers. Of

course, the force variation increases further for larger scan sizes.

An alternative to the scanned-stylus AFMs described above is described by Elings et al (U.S. Patent No. 5,025,658). This design, shown in Fig. 2, places the AFM cantilever 14 extremely close to the emitting surface of a laser diode 21. The laser light reflects off the cantilever, back into the laser itself. The reflections will cause optical interference that is detected at a photodiode 22 that is contained within the laser package. Laser diode 21 are attached to scanner 12 using a laser mounting member 23. A miniature optical interferometer is formed such that as cantilever 14 deflects the amount of light detected at photodiode 22 changes. Since the laser, photodetector, and the cantilever are closely coupled, the laser and detector always tracks the cantilever, independent of scan size.

This prior art system has a number of disadvantages, however. First, this type of optical interferometer only has sufficient sensitivity for AFM measurements if the laser and cantilever are very closely coupled, typically with less than 100 micron separation. This requires extremely precise alignment of the cantilever with respect to the laser. Second, the piezoelectric translator must carry the weight of a laser diode near the free end of the translator. This can cause a reduction in the mechanical resonant frequency of the translator, making the translator more susceptible to

vibrations. Also, because the laser is so close to the cantilever, it is not possible to view the cantilever and sample simultaneously with an optical microscope.

In addition, the optical interferometer used in the Fig. 2 AFM produces an output that changes periodically with distance. The position of cantilever 14 with respect to laser 21 is selected such that a deflection of cantilever 14 causes a change in the interferometer output. For example, the position could be selected so that positive cantilever deflections cause positive increases in the interference output. Then the force feedback will cause cantilever 14 to retract when the interference output increases. But because the interferometer output is periodic, sudden displacements of cantilever 14 can move it to a point where further deflections cause the interference signal to be opposite to that expected, i.e., decrease rather than increase. This sort of error will cause the feedback system to immediately jump the next period ("mode hop") of the interference signal. This makes accurate force control of the prior art scanned-stylus AFM of Fig. 2 very difficult.

Other versions of scanned-stylus AFMs have been built by Putman et al, *supra*, and commercial instruments have been produced by Topometrix, Inc. These designs are optical lever AFMs where the cantilever is scanned over a fixed sample. Both of these designs mount the laser and cantilever on the same scanning unit, so that they move together. This prior

art is shown schematically in Fig. 3. In Fig. 3 a focusing lens 30 is disposed between laser 10 and cantilever 14. This system has the disadvantage that scanner 12 has to carry the weight of laser 10, electronic leads to laser 10, focusing lens 30, and any mechanism for fine tuning the laser position on cantilever 14. All of these can reduce the mechanical resonant frequency of scanner 12 and transmit vibrations to cantilever 14. Also, in the case of a tube scanner, attachment of a laser to the interior of a scanner can make its exchange difficult in case of laser failure.

In addition, these designs have the laser beam 17, cantilever 14 and stylus 15 move with respect to a fixed position sensitive detector 16. So when cantilever 14 is scanned over the surface of sample 13, reflected laser beam 18 will move with respect to fixed position sensitive detector 16, even in the absence of any actual deflection of cantilever 14.

Other versions of scanned stylus AFMs have relied on scanned optical fibers used as interferometers or as a moving light source for the optical lever technique.

Another form of scanned-stylus AFMs use cantilevers that are instrumented with a piezoelectric or a strain gauge (copending application serial no. 08/009,076 and Tortonese et al, Transducers '91, 1991 International Conference on Solid-State Sensors and Actuators, San Francisco, CA, 24-27 June 1991, and Tortenese et al, Appl. Phys. Lett., 62, p. 834,

(1993), and produce a voltage or a change in resistance that depends on the deflection of the cantilever.

A number of the prior art AFMS, especially those relying on optical interferometers to detect cantilever deflection, closely couple the cantilever and the laser light source and/or the assembly for detecting the cantilever deflection. In some cases this separation is less than 100 microns. This close coupling makes it extremely difficult to also view the cantilever and the area of the sample that it is scanning with an optical microscope.

SUMMARY OF THE INVENTION

It is an object of the present invention to provide a novel scanned-stylus AFM that detects cantilever deflection by reflecting a laser beam off the back side of the cantilever.

It is a second object of the present invention to prevent scanning the cantilever out from under a fixed laser beam.

Another object of this invention is to provide a scanned-stylus AFM that minimizes the tracking force variation across the entire scan range, and does not create artificially "warped" images.

A further object of this invention is to automatically provide a signal that is proportional to the motion of the cantilever across the sample.

Another object of this invention is to provide an AFM satisfying one or more of the above objects and can also operate with the cantilever and sample covered by fluid.

Still another object of this invention is to allow sufficient separation between the laser light source and the cantilever to provide access for an optical microscope to view the cantilever and the area of the sample that the cantilever is scanning.

These and other objects are achieved according to the present invention by providing a new and improved optical lever scanned-stylus AFM. The AFM includes a scanning mechanism, a fixed light source, a cantilever attached to the scanning mechanism, a stylus mounted on the cantilever and an optical assembly mounted on the scanning mechanism which guides a light beam emitted from the light source onto a point on the cantilever during movement of the scanning mechanism. A position detector receives a light beam reflected from the cantilever and detects a deflection of the cantilever. The optical assembly will move with the scanning mechanism and guide the light beam to a spot on the cantilever while it is scanned across the sample, to avoid both scanning the cantilever out from under a fixed, unguided beam and movement of the beam spot on the cantilever.

The optical assembly that causes the light beam to track the cantilever also provides a means of measuring the actual motion of the scan. A portion of the scanning light beam may

be directed to an additional position sensitive detector and the output of this detector can indicate the actual motion of the scanner. Since there may be differences between the desired motion of the scanner and the actual motion of the scanner, this technique provides a means to measure and correct the problem.

The scanning mechanism may comprise a piezoelectric tube scanner, where the optical assembly may also be mounted in the tube scanner. The scanning mechanism may be comprised of two or more different scanning elements, as mentioned in U.S. Patent 5,198,715. One or more of the scanning elements may have asymmetric cutaways that allow mechanical or optical access to the cantilever.

The AFM according to the invention may also include an optical mirror mounted for receiving a light beam from the light source, which may be at an arbitrary location, and directing the light beam to the scanning optical assembly.

The AFM may also include a separate optical mirror mounted to reflect light from the sample and cantilever to an optical microscope assembly. This arrangement makes it possible to directly view the cantilever and areas of interest on the sample. The mirror may be totally reflecting with a hole or it may be a partially reflecting or dichroic mirror to allow the light beam used to measure cantilever deflection to pass through the mirror.

According to the invention, the position detector may be located at a point where all light beams reflected from a cantilever with a fixed bend during a full extent of its movement converge.

This AFM according to the invention uses a light source, usually a laser, which is mounted so that it is not moved by the scanning mechanism, and an optical assembly using any combination of lenses, mirrors, or other optical elements attached to a scanning mechanism (or "scanner"). The motion of one or more of the optical components, attached to the scanner, guides the laser beam so that it always strikes a fixed point on the cantilever, and at a fixed angle with respect to the cantilever.

These and other objects are also obtained by a method of operating an AFM having a remote light source, a cantilever and an optical assembly attached to a scanning mechanism, and a position detector, including the steps of generating a light beam, directing the light beam onto the cantilever using the optical assembly so that the light beam strikes a substantially fixed point on the cantilever during movement of the scanning mechanism, and receiving a reflected light beam reflected from the cantilever using the position detector to detect a deflection of the cantilever.

The method may further take the steps of splitting the light beam into a first beam which strikes the cantilever and a second beam which is directed to a second position detector.

The method focuses the first beam to a point source between a fixed end and a free end of the scanning mechanism and then focuses an image of said point source on said cantilever. The method also allows the lateral position of the point source to be changed while maintaining a substantially fixed vertical position of the point source while scanning the scanning mechanism.

BRIEF DESCRIPTION OF THE DRAWINGS

A more complete appreciation of the invention and any of the attendant advantages thereof will be readily obtained as the same becomes better understood by reference to the following detailed description when considered in connection with the accompanying drawings, wherein:

Fig. 1 is a simplified functional block diagram of a prior art optical lever scanned-stylus atomic force microscope;

Fig. 2 is a block diagram of a prior art scanned-stylus atomic force microscope incorporating a laser diode interferometer;

Fig. 3 is a block diagram of a prior art atomic force microscope that scans the stylus and also the laser light source;

Fig. 4 is a simplified block diagram of an optical lever scanned-stylus atomic force microscope according to a first embodiment of the present invention;

Fig. 4B is a diagram of a tube scanner having an asymmetric cut out.

Fig. 5 is a modification of the first embodiment shown in Fig. 4, with the addition of a removable fluid cell allowing operation of the sample covered by fluid.

Fig. 6 is a modification of the first embodiment shown in Fig. 4, where the laser is mounted at the side of the scanner;

Fig. 7 is a simplified schematic diagram of a scanned-stylus atomic force microscope according to a second embodiment of the present invention;

Fig. 8 is a simplified schematic diagram of a scanned-stylus atomic force microscope according to a third embodiment of the present invention;

Fig. 9 is a modification of the third embodiment shown in Fig. 8, having multiple lenses;

Fig. 10 is a simplified schematic diagram of a fourth embodiment according to the present invention;

Fig. 11 is a simplified schematic diagram of a scanned-stylus atomic force microscope according to the invention illustrating the placement of the position sensitive detector;

Fig. 12 is a simplified schematic diagram of a first modification of the atomic force microscope shown in Fig. 11;

Fig. 13 is a simplified schematic diagram of a second modification of the atomic force microscope shown in Fig. 11; and

Fig. 14 is a flowchart of a method of operating the atomic force microscope of the invention.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

Referring to the drawings, and more particularly to Fig. 4, a first embodiment of the invention will be described. The AFM illustrated in Fig. 4 contains a light source 10, such as a laser, emitting a beam 41 which is directed through or alongside scanner 12. Scanner 12 is typically a piezoelectric translator, but could also be made of electrostrictive, magnetostriuctive or other similar material. The scanner 12 is typically a tube translator, made of one or more piezoelectric tubes, as described in U.S. Patent 5,198,715, but could be of different shape and constructed of multiple scanning elements. A first lens 40 is disposed between the laser 10 and scanner 12, or attached to a fixed part of scanner 12. An optical assembly 43 is mounted on scanner 12 for guiding beam 44 onto cantilever 14. Preferably, the optical assembly 43 is mounted to the scanner using a mounting ring, which may be made of metal or an insulating material, or may be mounted using an adhesive. Optical assembly 43 can also be mounted on the exterior of scanner 12 and positioned such that beam 44 is guided onto cantilever 14. The AFM of Fig. 4 can also include a partially reflective mirror or a dichroic mirror 45 and optical microscope 46 for viewing cantilever 14 and sample 13. The mirror 45 may be attached to

the optical microscope 46, to the scanner 12 or mounting member 42, or to a separate fixed mounting structure (not shown). The beam 47 reflected from cantilever 14 is detected by position sensitive detector 16.

The cantilever 14 is attached to the scanner 12 via mounting member 42, and possible additional mounting elements (not shown). The additional mounting elements can allow the cantilever assembly to be exchanged for operation in fluid (U.S. Patent 4,935,090) or exchanged with probes for other scanning microscopes like the scanning tunneling microscope. The shape of mounting member 42 allows the beam 47 reflected from cantilever 14 to be detected, and allows other mechanical and optical access to cantilever 14. Parts mechanically similar to mounting member 42 made from metal or insulators have been used in the prior art, but, according to the present invention mounting member 42 is constructed from piezoelectric material and used as an actuator for the vertical, or Z direction. Note that the cut out on mounting member 42 need not be symmetric for the actuator to move substantially in the Z direction. Fig. 4B provides a more detailed view of the scanner 12 and mounting member 42, in particular the cut out which is labeled 42b.

For operation of an atomic force microscope where the sample 13 and cantilever 14 are covered by fluid, it is usually necessary to construct a fluid cell that presents a flat surface to incoming and outgoing light beams. One such

cell is shown in Fig. 5. This fluid cell 48 may be constructed of glass, plastic or other transparent material. This fluid cell 48 is constructed such that at least the surfaces of the cell closest to the cantilever are at the same angle with respect to the incoming light beam 44 as is the cantilever 14. In this way, because of optical symmetry, the light beam leaving the fluid cell 47 will not change its angle when fluid 49 is added to fluid cell 48. It may be advantageous to have both surfaces of the fluid cell 48 be at the same angle as the cantilever 14. In addition, fluid cell 48 is removable and can be exchanged for mounting elements that are optimized for a contact AFM, oscillating probe AFM, scanning tunneling microscopes or other scanning probe microscopes.

As cantilever 14 and stylus 15 are scanned over the surface of sample 13 the beam 44 "follows" the cantilever, i.e. the beam is incident on essentially a fixed spot on cantilever 14 during movement of cantilever 14. The movement of reflected beam 47 is detected by position detector 16. The problem of cantilever 14 moving out from under beam 44 is minimized or eliminated by using the motion of the optical assembly 43 attached to a moving part of scanner 12 (in this example the piezoelectric tube scanner) to guide beam 44 to always strike the same, or substantially the same spot on scanning cantilever 14. The changing position and angle of optical assembly 43 with respect to stationary incoming beam

41 can be used to bend beam 41 in a controlled way so that the bent beam 44 always strikes the same or substantially the same spot on cantilever 14 as it is scanned over sample 13. This will occur if the position of the components of optical assembly 43 is chosen such that the magnification of optical assembly 43 matches the motion produced by scanner 12.

For example, consider the case where scanner 12 includes an XYZ piezoelectric tube translator with an optical assembly 43 attached to the tube. If the tube translator is scanned back and forth, the amount of translation of a point on the tube depends on how far the point is from the fixed end (the fixed end does not move, the free end moves the maximum distance, and intermediate points move some fraction of the maximum). If the optical assembly 43 is placed somewhere between the fixed and free ends, it will move less than a cantilever 14 placed at the free end. The optical assembly may also be mounted in the interior of the tube so that the light beam also propagates through the tube. The scanning motion of optical assembly 43 will cause the light beam 44 to move in a periodic way. Since optical assembly 43 will typically move less than cantilever 14, optical assembly 43 must provide some optical magnification so that the output light beam 44 will move the same distance as the cantilever 14. The moving optical assembly 43 will cause the light beam to accurately follow the moving cantilever 14 if the optical assembly 43 is located so that the optical magnification is

matched to a property that can be called the "mechanical amplification" of the scanner 12, or the ratio of the optical assembly 43 motion to the cantilever 14 motion. If the construction and position of optical assembly 43 are such that these magnifications are matched, the light beam 43 will track the moving cantilever 14.

Fig. 6 is a modification of the embodiment shown in Fig. 4. The light source has been positioned to the side of the scanner 12, and a mirror 50 has been mounted to direct beam 41 from the laser 10 through optical assembly 43 and onto cantilever 14.

A second embodiment of the invention is shown in Fig. 7. This AFM includes an optical arrangement incorporating two lenses. A first lens 60 is used to focus beam 61 to a point source 62 at an intermediate point on scanner 12. Lens 60 can be any of a variety of lenses, such as a convex lens or concave lens, so long as point source 62 is formed. Point source 62 could also be created by a diverging lens placed below the desired point source, by an illuminated pinhole, by an optical fiber, by a laser diode or other laser point source, for example. This embodiment also contains a mechanism for steering the light source 10 and/or lens 60 to move the point source 62 in the lateral direction. Moving the point source 62 also moves the position of the focused spot of light beam 68, allowing this beam to be adjusted for varying positions of cantilever 14. The steering mechanism is

constructed in such a way that while the horizontal position of point source 62 may be altered, the vertical position, and hence distance from lens 63, is essentially unchanged. Point source 62 forms the object for a second lens 63 mounted to a moving point on the scanner 12. The vertical position and the focal lengths of both lenses are chosen so that the focused image is formed at the cantilever 14. When cantilever 14 is scanned, lens 63 will move laterally relative to the point source object 62. This means that the focused image in the plane of the cantilever will move laterally also. The placement of the lenses can and has been determined by trial and error, resulting in a successful design. Alternatively, a suitable lens position can be computed by the following procedure, involving standard optical calculations. Some simple example calculations are listed below. It may of course be necessary to take into account various optical aberrations, not discussed here. (see, for example, Hecht and Zajac, Optics, 3rd Ed., Addison-Wesley, Menlo Park (1976)).

If the steering lens 63 is moved perpendicular to the optical axis with respect to the point source object by a distance Δo , the focused image will move by a distance Δi . The distance Δi is the sum of the lens motion Δo plus additional motion due to the magnification of the optical system. Specifically, $\Delta i = M_i \cdot \Delta o$. Here the optical magnification of the lens system M_i is given by y_i/y_o , where y_i is the distance between the lens and the focused image on the

cantilever, and y_o is the distance between the lens 63 and the point source object 62.

For a given motion of scanner 12, cantilever 14 moves a distance Δc with respect to the point source 62 that is greater than the lens 63 motion Δo . The ratio of the cantilever motion Δc to the lens motion Δo may be called the mechanical magnification of the scanner M_s . This factor M_s depends on the position of the steering lens 63 and the cantilever 14 with respect to each other and with respect to the scanner 12. This quantity may be calculated theoretically, or measured for a given scanner by a variety of means. It is necessary to arrange the magnification M_l of the lens so that the motion of the focused image Δi is approximately the same as the cantilever motion Δc . In this case the focused spot of light beam 44 moves the same distance as the cantilever 14 as it scans over the sample. Thus, the light beam 44 is incident on a fixed spot on cantilever 14 throughout its motion of scanning.

In the case where $\Delta i = \Delta c$, the optical magnification M_l and the mechanical magnification of the scanner M_s are related in the following manner:

$$M_s = \Delta c / \Delta o = \Delta i / \Delta o = (\Delta o + M_l \cdot \Delta o) / \Delta o = 1 + M_l$$

The choice of lenses and their positions may be determined by trial and error or with the above equations. It should be noted that there are a whole family of lens and position sets that will give satisfactory results. In

linear scans, as described in U.S. Patent No. 5,051,646, to correct AFM data after it has been stored, or to use a feedback system to correct for scanner distortions in real time. Using laser beam deflections to correct for piezoelectric scanner distortions has been described by Marshall in U.S. Patent No. 5,172,002.

Fig. 8 shows a third embodiment of the invention that uses a single lens. In this design a parallel laser beam 70 is focused onto a cantilever using a steering lens 71 mounted close to the free end of a scanner. In practice, lens 71 is mounted at least 70% of the distance from the fixed end of the scanner 12 to the cantilever 14. Focussing the parallel beam allows the focused spot to follow the center of the lens. Lens 71 moves almost the same distance and angle as the cantilever. Since the parallel rays of the parallel light beam 70 will focus at a point a fixed distance below the center of lens 71, moving the lens with the cantilever will cause the focused laser spot to track moving cantilever 14. The performance of this embodiment is determined by how close lens 71 can be placed to cantilever 14 in practice. As lens 71 is placed farther from cantilever 14, it will not move as far as cantilever 14 and the tracking accuracy will decrease. This steering lens could also be used as the objective in a optical microscope, allowing optical viewing of the cantilever 14 and sample 13.

Fig. 9 shows another alternative optical arrangement, that is a variation of the AFM shown in Fig. 8. In this arrangement a fixed lens 80 is placed above steering lens 71. Fixed lens 80 weakly focuses the beam emitted from light source 10 before it reaches the steering lens. The lenses and their positions are chosen by standard optical calculation where the focal length f_1 of fixed lens 80 is much longer than the sum of focal length f_2 of steering lens 72 and the separation between lenses 72 and 80. The focal length f_2 is chosen so that it focuses the light beams from lens 80 to a spot on cantilever 14. This accomplishes two things. First, it allows the size of steering lens 71 to be smaller, and hence the weight to be less. It is desirable to minimize the weight that scanner 12 must carry to maintain a high mechanical resonant frequency and thus immunity from vibration. Second, fixed lens 80 may be chosen to offset or reduce coma errors introduced at steering lens 71 due to the fact that the angle of lens 71 with respect to the incoming light beam changes as scanner 12 moves steering lens 71 and cantilever 14.

A fourth embodiment of the invention is shown in Fig. 10. In this embodiment, the parallel beam emitted by laser 10 is focused so that a spot will result on the cantilever. A steering mirror 90 is placed at a point on scanner 12 so that the translation and angular swing of mirror 90 always guides the laser beam to a moving cantilever. A single mirror could

be used for single axis scans, two mirrors could be used for complete two axis scans. A single mirror is shown for clarity. The required position of the mirror 90 will depend on the construction details of scanner 12, but the appropriate position can be found very simply by trial and error. This may be done by varying the position of the mirror 90 with respect to the cantilever until the light beam reflected off the mirror 90 accurately tracks the cantilever 14 throughout its scanning motion.

Since the embodiments shown in Figs. 8-10 also create a light beam that moves in proportion to the scanner motion, this light beam motion can be used to measure, calibrate or correct the scanner motion as shown in Fig. 7 and described above, i.e., a beam splitter and second position detector could be added.

All of the embodiments described above allow sufficient clearance (up to several inches) between the light source 10 and the cantilever 14 to allow access for an optical microscope. As mentioned, some of the lenses or optical elements used for causing the laser to track the cantilever could be used as part of the optical microscope.

The present invention also provides large scans with uniform tracking forces over the entire scan. As mentioned previously, as cantilever 14 is scanned over a sample 13, both the position and angle of cantilever 14 with respect to a fixed position sensitive detector 16 will change. In the

prior art, this caused the reflected laser beam to move on the position sensitive detector, mimicking an actual deflection of the cantilever. These "false deflections" present in prior art AFMs, which were described by Baselt et al, *supra*, distort images with "bowing," i.e., flat surfaces appear curved. In addition, the feedback system is programmed to keep the position of the reflected laser at the position sensitive detector constant. It will read these "false deflections" as real deflections and adjust the actual deflection of the cantilever to compensate for the errors. Adjusting the actual deflection of the cantilever, changes the tracking force exerted by the cantilever stylus. For many samples, it is necessary to minimize the tracking force to avoid damage to the surface (Hoh and Hansma, *supra*). The changing tracking force introduced by the prior art AFM makes it impossible to reduce the tracking force to less than the amount that it changes over the scan. In practice, the resultant tracking force may be much larger than delicate samples can withstand. The present invention solves this problem in two ways. First, as described above, ensures that the light beam strikes essentially the same spot on the cantilever as the cantilever is scanned over the surface. This minimizes or eliminates "false deflections" that are caused by variations in the bend of the cantilever as discussed by Baselt, *supra*. It also ensures that there are no "false deflections" due to the cantilever being scanned out from under the light beam.

Secondly, minimizing spurious force variations and eliminating "warped" images is detailed below. For optimal performance, techniques shown in Figs. 5-10 are intended to be used in combination with one or more of the techniques shown in Figs. 11-13 and described below.

Fig. 11 shows a fifth embodiment of the invention directed to solving the problem described above. In this embodiment, the incoming light beam 101 tracks the moving cantilever 14 by one of the means shown in Figs. 7-10, or by any other similar means. Now as cantilever 14 scans over the surface of sample 13, both the position and angle of the reflected beam 102 change. In Fig. 11, three different incoming (101) and reflected (102) laser beams are shown, corresponding to three different positions of cantilever 14. As the cantilever 14 scans over surface 13, the angle of the cantilever 14 with respect to the position sensitive detector 16 changes in a predictable and reproducible way. The light beams 101 and 102 are shown schematically as thin lines for clarity, but are actually focused to a small spot onto the cantilever 14 and diverge to the position sensitive detector 16 at point 104 as shown in Figs. 5-10.

From Fig. 11 it is clear that there is a position in space that all of these reflected laser beams 102 converge, provided that the angle traced out by the scanner 12 is small (in practice, the angles traced out are much less than one degree; the angles shown in Fig. 11 are approximately ± 5

degrees). This convergence can be understood in the following way. As the cantilever 14 is scanned over surface 13, the angle of the cantilever 14 with respect to position sensitive detector 16 will change slightly. For example, in Fig. 11, as cantilever 14 is scanned to the left, the angle of cantilever 14 will become shallower, and as cantilever 14 is scanned to the right the angle gets steeper. If one were to plot the angle of cantilever 14 over its entire scan range, the result would be a surface with a slightly convex curvature. The degree and type of curvature of this surface depend on the details of the motion of the scanner 12. In some cases it may be sufficient to consider this surface as a part of a sphere where the radius is given by the distance between the cantilever and the apparent pivoting point of the scanned motion. This convex surface formed by the scanning cantilever 14 will act like a convex mirror of the same curvature. For this reason, this convex surface acts in a way that will focus all reflected beams from a point source to another point, for example the point of convergence 104 shown in Fig. 11. The point at which the beams converge can be determined by geometric construction, or by calculation from standard optical formulas for convex mirrors (see, for example, Hecht and Zajac, *supra*). If position sensitive detector 16 is placed at or near the focus created by the traced out concave surface, the AFM will be insensitive to the motion of cantilever 14 caused by the scanner 12.

In this embodiment, the position sensitive detector 16 is placed at the point of convergence 104. If position sensitive detector 16 is placed near point of convergence 104, similar results may be obtained, but optimal precision is obtained at point of convergence 104. In this case, the changing angle and lateral position of cantilever 14 no longer moves the reflected laser beam 102 on position sensitive detector 16. In this way "false deflections" are eliminated. Also in practice it is not necessary to determine curvature of the surface created by the scanning cantilever. Instead it is possible to empirically determine the optimum position of the position sensitive detector 16. This is done by scanning the cantilever on a very flat surface or actually not touching any sample, and measuring the change in the position of the signal from the position sensitive detector. The amount of change in this signal is a measure of the amount of "false deflection" being seen by the system. The position sensitive detector may be moved closer or further from the cantilever until these "false deflections" are minimized. It is also possible with this technique to eliminate apparent curvatures that appear because of the pendulum-like motion of the scanner.

Fig. 11 also shows an alternate embodiment where an optional mirror 103 is used to redirect portions 106 of the reflected laser beams 102 so that the point of convergence occurs at another position. This allows the position

sensitive detector 105 to be put in a more convenient location.

Fig. 12 shows a modification of the embodiment of Fig. 11 where a relay lens 110 is used to transfer the point of convergence to another more convenient position. Lens 110 may also be used for adjusting the size of the reflected laser beam 102 so that it is optimized for the position sensitive detector 16. It is of course possible to use other lenses using standard optical practice to adjust the rate of convergence of beams 102 to make the convergence point 104 occur at other desired locations. A mirror could also be used in this embodiment anywhere between the cantilever and the position sensitive detector in the same manner as shown in Fig. 11 to direct the point of convergence to a different position.

Fig. 13 shows an alternate embodiment that uses a single concave mirror 120 to redirect the point of convergence shown in Figs. 11-12 to a more convenient position. In this case the single concave mirror 120 replaces the flat mirror 103 shown in Fig. 11 and the relay lens 110 shown in Fig. 12.

A method of operating the AFM according to present invention will now be described. As shown in Fig. 4, for example, a light beam is generated and then directed onto cantilever 14 using optical assembly 43 so that the light beam strikes substantially a fixed point on cantilever 14, during movement of the scanning mechanism. The striking of

substantially a fixed point is illustrated in Fig. 13, where light beams 101 strike cantilever 14 while it is scanned across sample 13. The light beam reflected from cantilever 14 (47 in Fig. 4) is received by position detector 16 which can detect deflections of cantilever 14.

Also illustrated in Fig. 4 is the splitting of beam 44 using splitter 45 and the cut out in mounting member 48 to allow access of an optical microscope 46, while in Fig. 7 the beam 68 is split using splitter 65 to direct a portion of the beam 68 to a second position detector 66.

Fig. 14 is a flowchart of a modification of the method of the invention where the location of the position detector is determined. First, in step 14-1, the light beam reflected from the cantilever is measured while the scanner 12 is scanned over a full extent of its movement on a very flat surface or while actually not touching any sample. The change in position in the measured signal is then determined using position sensitive detector 16 (step 14-2). The amount of change in this signal is a measure of the amount of "false deflection" being seen by the system. The position sensitive detector is then moved closer or further from the cantilever (along the optical axis of the reflected beam) and the scanning process repeated (step 14-3) a desired number of times until these "false deflections" are minimized (step 14-4). Position detector 16 is then placed at this location of minimum change (step 14-5).

While the invention has been described with reference to several specific embodiments, those skilled in the art will be able to make various modifications to the described embodiments without departing from the true spirit and scope of the invention. For example, an AFM that scans using other optical elements such as prisms instead of lenses or mirrors, or other combinations of such elements to keep the laser focused on a scanning cantilever, is within the intended scope of the invention. It is therefore to be understood that the within the scope of the appended claims, the invention may be practiced other than as specifically described herein.

Although what has been described is a contact AFM, where the stylus is in constant contact with the surface, the described invention can also be used in applications where the cantilever is oscillated, such as magnetic force microscopy (Martin and Wickeramasinghe, Appl. Phys. Lett., 50, pg. 1455 (1987), Non-contact Topography, Durig et al, Phys. Rev. Lett., 53, p. 1045, (1988)) and as a jumping probe microscope where the stylus is repeatedly lifted off the surface during a scan (U.S. Pat. Application 08/009,076).

5. An atomic force microscope as recited in Claim 1, wherein said scanning mechanism comprises:

a piezoelectric tube scanner; and

a mounting member attached to said tube scanner and made of piezoelectric material, said cantilever being attached to said mounting member.

6. An atomic force microscope as recited in Claim 3, further comprising an optical mirror mounted in or in the vicinity of said tube scanner for receiving a light beam from said light source and directing said light beam to said optical assembly.

7. An atomic force microscope as recited in Claim 1, wherein said optical assembly comprises a steering lens.

8. An atomic force microscope as recited in Claim 1, further comprising:

an optical microscope; and

an optical beam splitter or dichroic mirror mounted to receive a light beam guided by said optical assembly and direct light reflected from said cantilever and sample to said optical microscope.

9. An atomic force microscope as recited in Claim 1, further comprising:

a second position detector; and

a beam splitter for directing a portion of light emitted from said light source onto said second position detector,

wherein said beam splitter is mounted between said optical assembly and said cantilever.

10. An atomic force microscope as recited in Claim 1, further comprising a lens mounted between said light source and said scanning mechanism.

11. An atomic force microscope as recited in Claim 1, wherein said optical assembly comprises means for producing a point source of light between a fixed end and a free end of said scanning mechanism.

12. An atomic force microscope as recited in Claim 11, wherein:

 said scanning mechanism comprises a piezoelectric tube scanner; and

 said optical assembly comprises a focus lens mounted at an arbitrary position, and a steering lens mounted in or alongside said scanner, said point source being formed between said focus lens and said steering lens.

13. An atomic force microscope as recited in Claim 12, wherein said focus lens and said steering lens focus an image of said point source on said cantilever.

14. An atomic force microscope as recited in Claim 12, further comprising a steering system for moving a position of the point source in the lateral direction, but maintaining an essentially fixed vertical position, keeping a vertical distance between said point source and said steering lens substantially constant.

15. An atomic force microscope as recited in Claim 12, wherein a distance moved by said steering lens during scanning of said cantilever is Δo , a distance moved by said image during said scanning is Δi , y_i is a distance between said steering lens and said image, and y_o is a distance between said steering lens and said point source, a magnification of said optical assembly $M_t = y_i/y_o$, and a mechanical magnification of said system M_s is chosen such that:

$$M_s = \Delta i/\Delta o = 1 + M_t.$$

16. An atomic force microscope as recited in Claim 1, wherein said optical assembly comprises:

means for forming an object using said light beam; and a lens adapted to focus said image on said cantilever; wherein a distance moved by said lens during scanning of said cantilever is Δo , a distance moved by said image during said scanning is Δi , y_i is a distance between said lens and said cantilever, and y_o is a distance between said lens and said image, a magnification of said optical assembly $M_t = y_i/y_o$, and a mechanical magnification of said system M_s is chosen such that:

$$M_s = \Delta i/\Delta o = 1 + M_t.$$

17. An atomic force microscope as recited in Claim 1, wherein said optical assembly comprises:

a first lens for focussing light from said light source to a point source between a fixed end and a free end of said scanning mechanism; and

a steering lens mounted between said point and said cantilever.

18. An atomic force microscope as recited in Claim 1, wherein said light source comprises a laser which emits a parallel laser beam; and

wherein said optical assembly comprises a lens mounted on said scanning mechanism at a point that is at least 70% of the distance from a fixed end of said scanning mechanism to said cantilever.

19. An atomic force microscope as recited in Claim 1, wherein said optical assembly comprises:

a fixed lens which weakly focusses light from said light source into a beam; and

a steering lens mounted between said fixed lens and said cantilever, that forms a focused spot on the cantilever.

20. An atomic force microscope as recited in Claim 1, wherein said optical assembly comprises a mirror mounted on said scanning mechanism.

21. An atomic force microscope as recited in Claim 20, wherein said mirror is mounted on said scanning mechanism such that, during movement of said scanning mechanism, the light beam reflected off said mirror will strike substantially a fixed spot on said cantilever, or track the motion of said cantilever in one direction.

22. An atomic force microscope as recited in Claim 1, wherein said optical assembly comprises:

a first mirror mounted on said scanning mechanism; and
a second mirror mounted on said scanning mechanism;
said first mirror being used in scans in a first direction and
said second mirror being used in scans in a second direction.

23. An atomic force microscope as recited in Claim 22,
wherein said first and second mirrors are mounted on said
scanning mechanism such that, during movement of said scanning
mechanism, a light beam reflected off each of said first and
second mirrors will strike substantially a fixed spot on said
cantilever, and track motion of said cantilever in one
direction.

24. An atomic force microscope as recited in Claim 1,
wherein said position detector is located at a point where all
light beams reflected from said cantilever converge when said
cantilever is undeflected during a full extent of movement of
said scanning mechanism.

25. An atomic force microscope as recited in Claim 24,
further comprising:

a second position detector; and
a beam splitter for directing a portion of light beams
reflected from said cantilever onto said second position
detector.

26. An atomic force microscope as recited in Claim 24,
further comprising a relay lens mounted between said
cantilever and said position detector for relaying light beams
reflected from said cantilever to a desired location.

27. An atomic force microscope as recited in Claim 24, further comprising a relay mirror mounted between said cantilever and said position detector for relaying light beams reflected from said cantilever to a desired location.

28. An atomic force microscope as recited in Claim 1, wherein said position sensitive detector is located at or near a point where a minimum deflection is measured when said cantilever is undeflected and scanned over a full extent of movement of said scanning mechanism.

29. A method of operating a scanning probe microscope having a light source, a cantilever and an optical assembly attached to a scanning mechanism, and a position detector, comprising:

generating a light beam;

directing said light beam onto said cantilever using said optical assembly so that said light beam strikes a substantially fixed point on said cantilever during movement of said scanning mechanism; and

receiving a reflected light beam reflected from said cantilever using said position detector to detect a deflection of said cantilever.

30. A method as recited in Claim 29, further comprising: splitting said light beam into a first beam which strikes said cantilever and a second beam which is directed to a second position detector.

31. A method as recited in Claim 29, wherein said directing step comprises:

forming a point source between a fixed end and a free end of said scanning mechanism.

32. A method as recited in Claim 31, wherein said directing step further comprises:

focusing an image of said point source on said cantilever.

33. A method as recited in Claim 31, further comprising: moving a lateral position of said point source while maintaining a substantially fixed vertical position of said point source while scanning said scanning mechanism.

34. A method as recited in Claim 32, wherein said optical assembly comprises a focus lens, and a steering lens mounted on said scanning mechanism, said point source being formed between said focus lens and said steering lens, a distance between said steering lens and said image being y_1 , and a distance between said steering lens and said point source being y_0 , said method further comprising:

scanning said cantilever;

moving said optical assembly a distance Δo during said scanning;

moving said image a distance Δi during said scanning;

defining a magnification of said optical assembly as $M_t = y_1/y_0$; and

selecting a mechanical magnification $M_s = \Delta i/\Delta o = 1 + M_t$.

35. A method as recited in Claim 29, wherein said directing step further comprises:

weakly focusing said light beam into a weakly focused beam; and

focusing said weakly focused beam to a focused spot onto said cantilever.

36. A method as recited in Claim 29, further comprising:

locating said position detector at a point where all light beams reflected from said cantilever converge when said cantilever is undeflected during a full extent of movement of said scanning mechanism.

37. A method as recited in Claim 36, further comprising: splitting said light beams reflected from said cantilever into a first beam which is directed to said position detector and a second beam which is directed to a second position detector.

38. A method as recited in Claim 29, further comprising: determining a point where all light beams reflected from said cantilever converge when said cantilever is undeflected during a full extent of movement of said scanning mechanism; relaying said light beams reflected from said cantilever to a desired position.

39. A method as recited in Claim 38, further comprising: using a relay lens to relay said light beams reflected from said cantilever.

40. A method as recited in Claim 38, further comprising:

using a relay mirror to relay said light beams reflected from said cantilever.

41. A method as recited in Claim 29, further comprising:
measuring a change in said reflected light beam when said cantilever is undeflected and scanned over a full extent of movement of said scanning mechanism; and
locating said position detector at a point where said change is a minimum.

ABSTRACT OF THE DISCLOSURE

A scanned-stylus atomic force microscope (AFM) employing the optical lever technique, and method of operating the same. The AFM of the invention includes a light source and a scanned optical assembly which guides a light beam emitted from the laser source onto a point on said cantilever during scanning thereof. A moving laser beam is thus created which will automatically track the movement of the cantilever during scanning. The invention also allows the laser beam to be used to measure, calibrate or correct the motion of the scanning mechanism, and further allows viewing of the sample and cantilever using an optical microscope.

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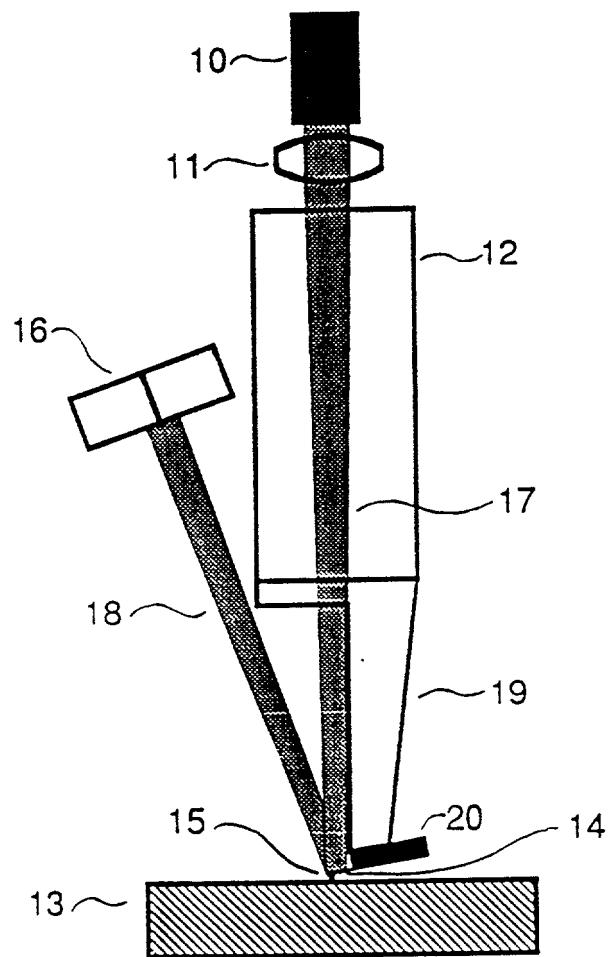


FIG. 1
(PRIOR ART)

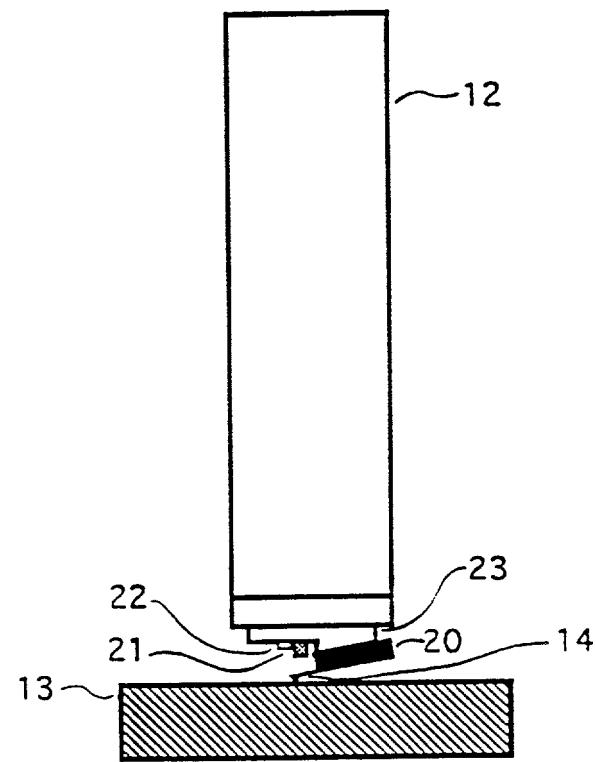


FIG. 2
(PRIOR ART)

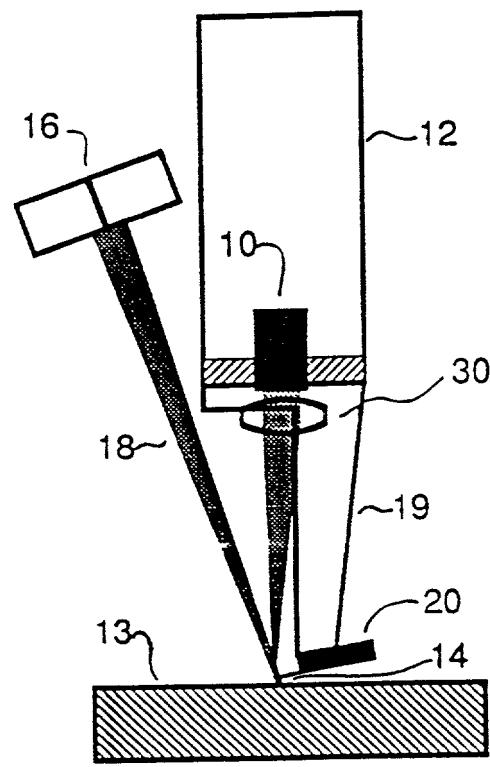


FIG. 3
(PRIOR ART)

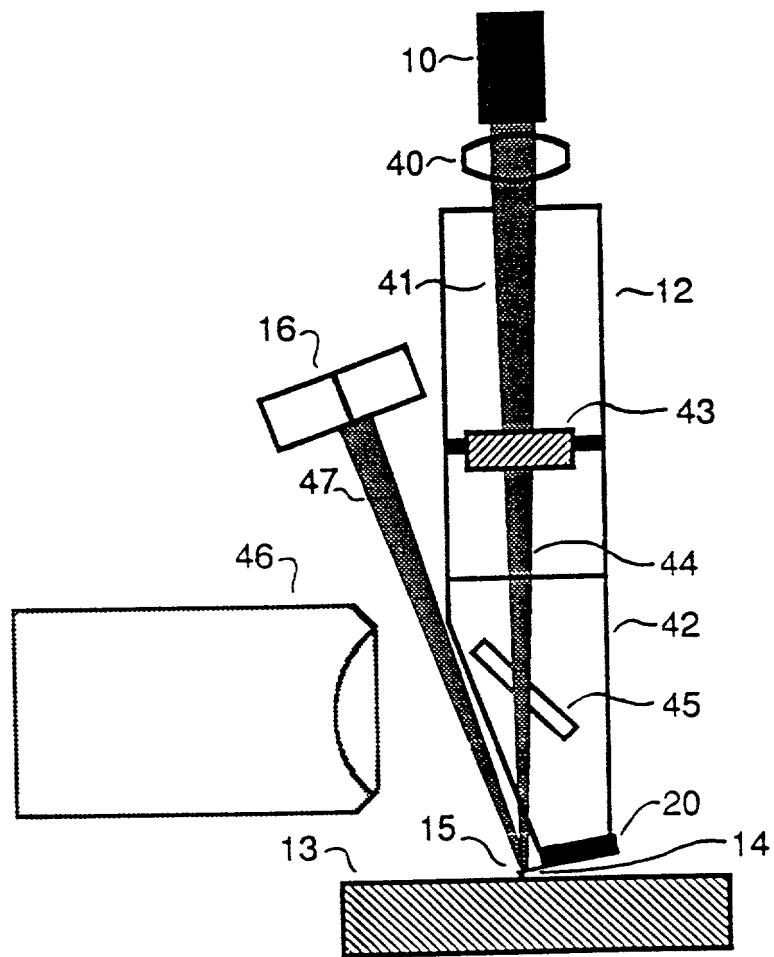


FIG. 4

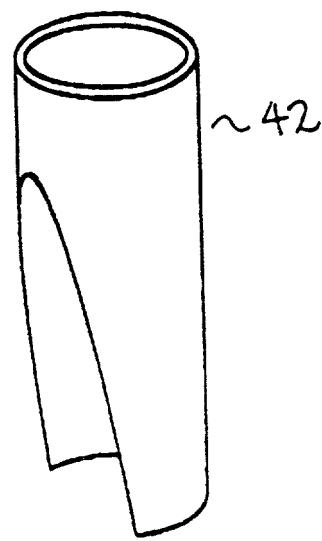


FIG. 4B

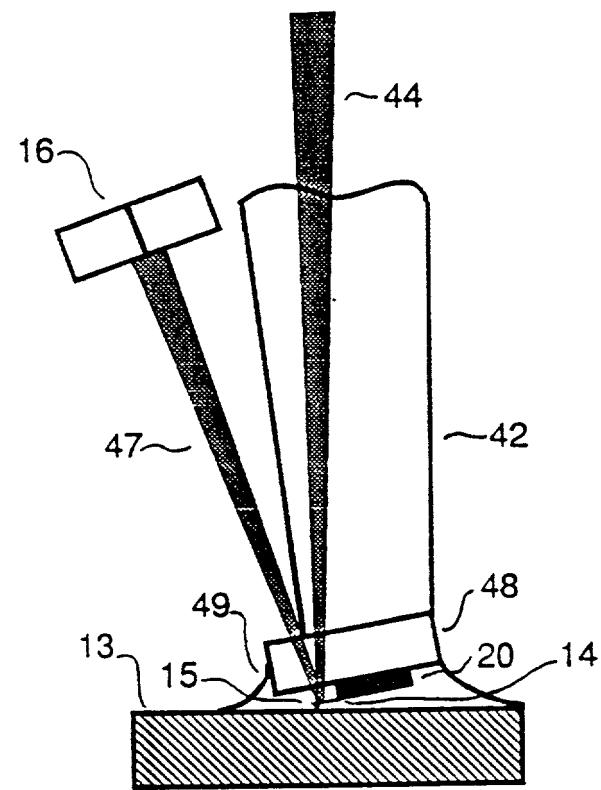


FIG. 5

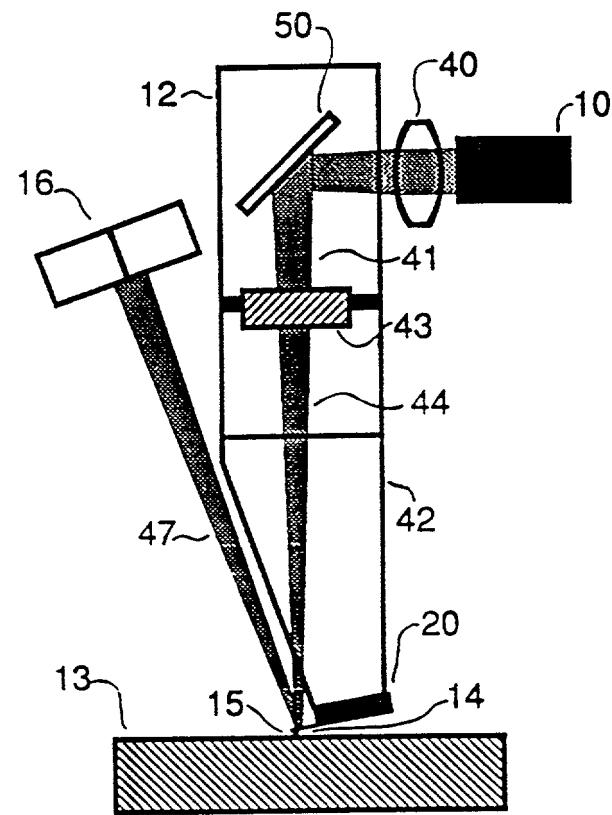


FIG. 6

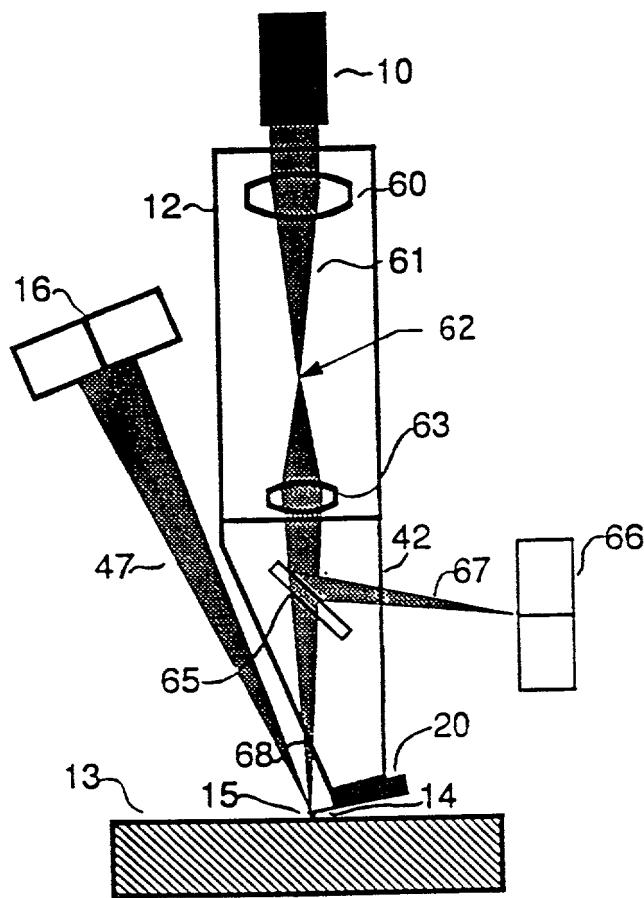


FIG. 7

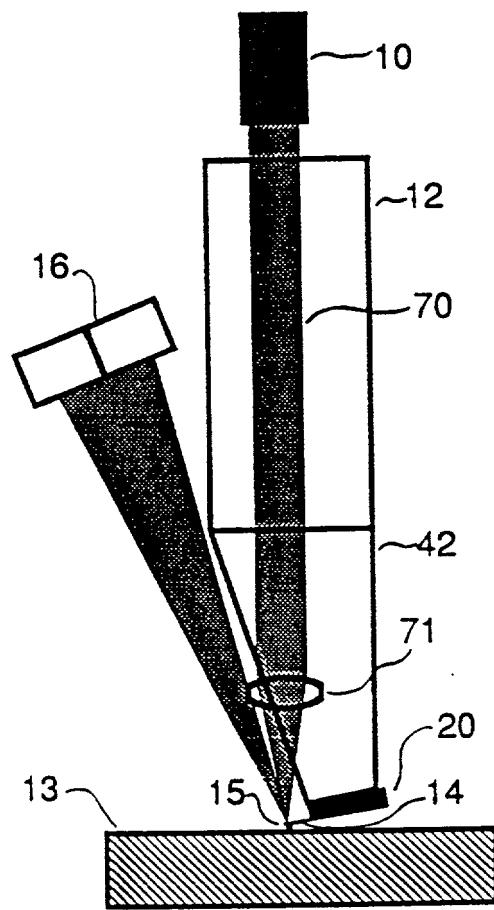


FIG. 8

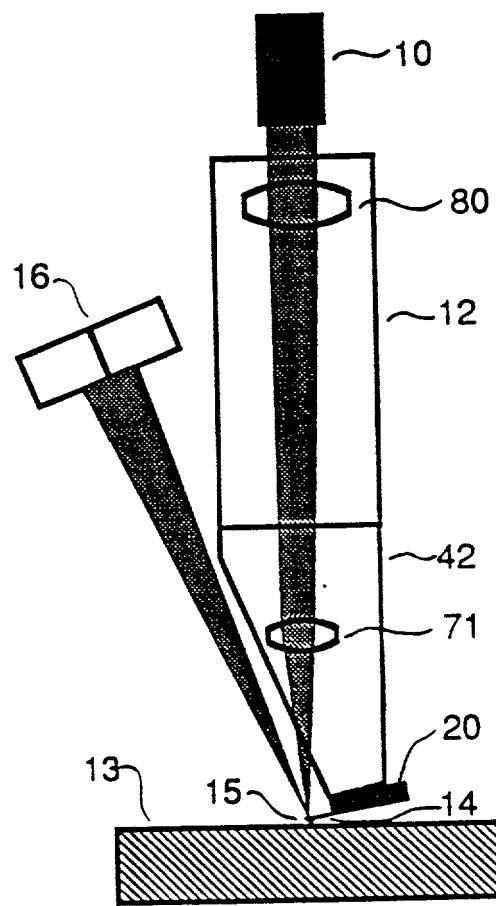


FIG. 9

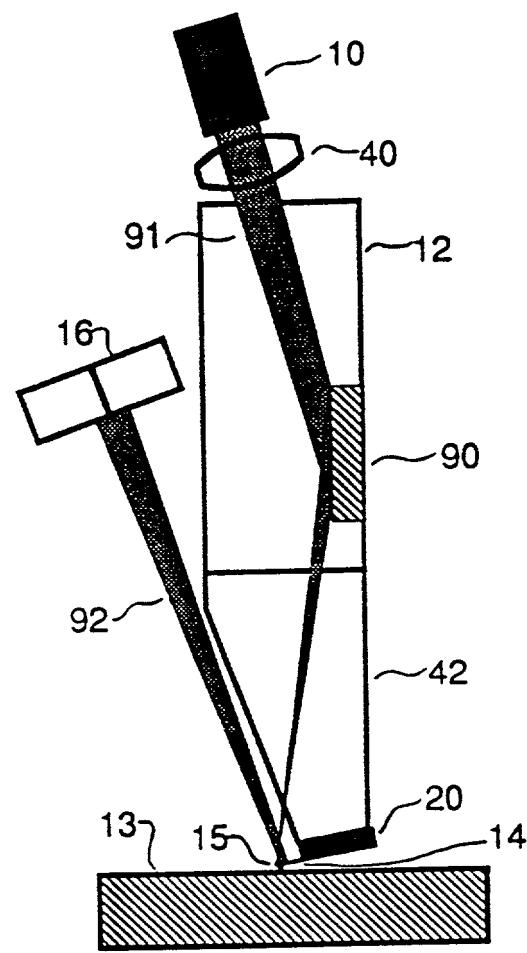


FIG. 10

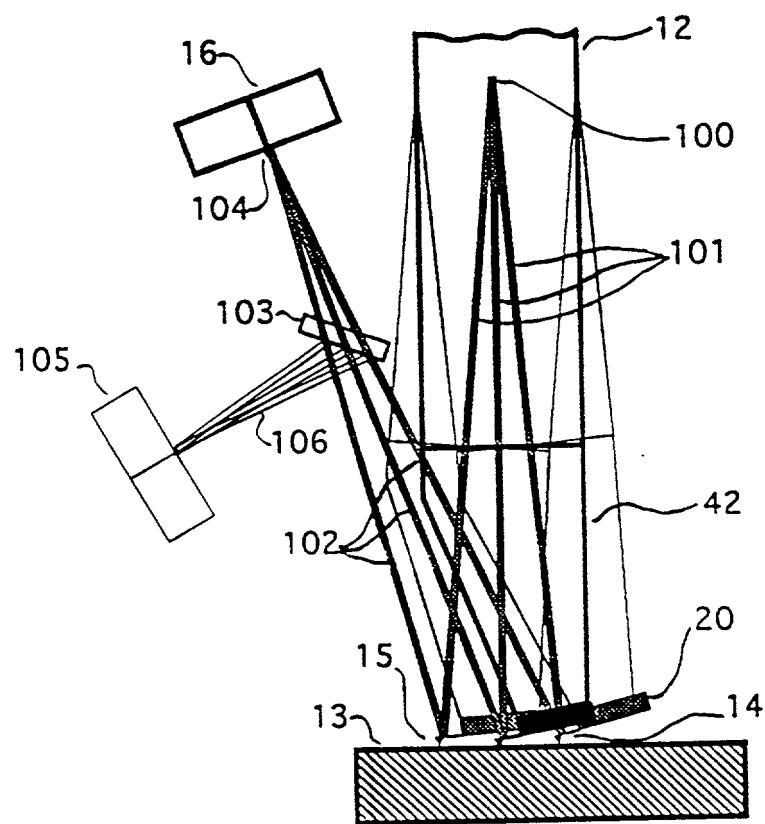


FIG. 11

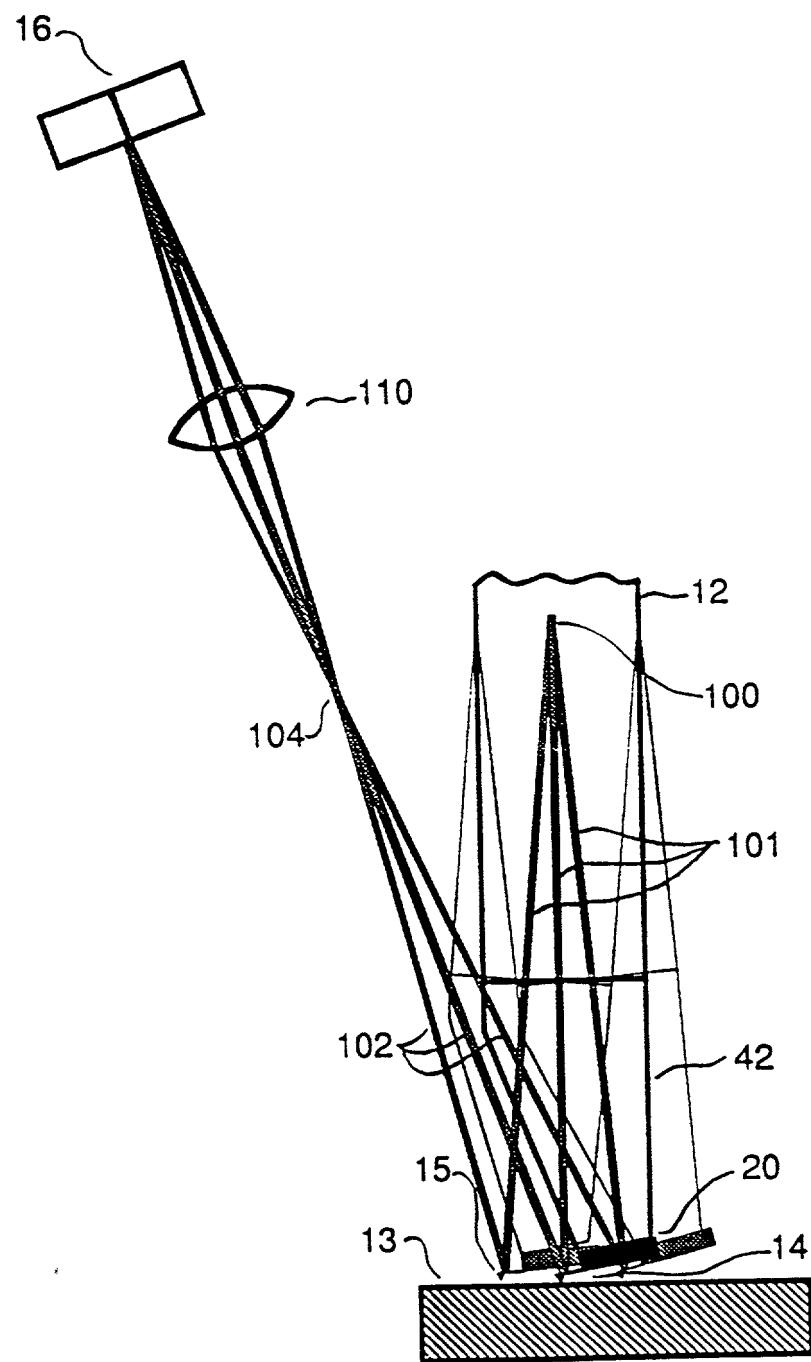


FIG. 12

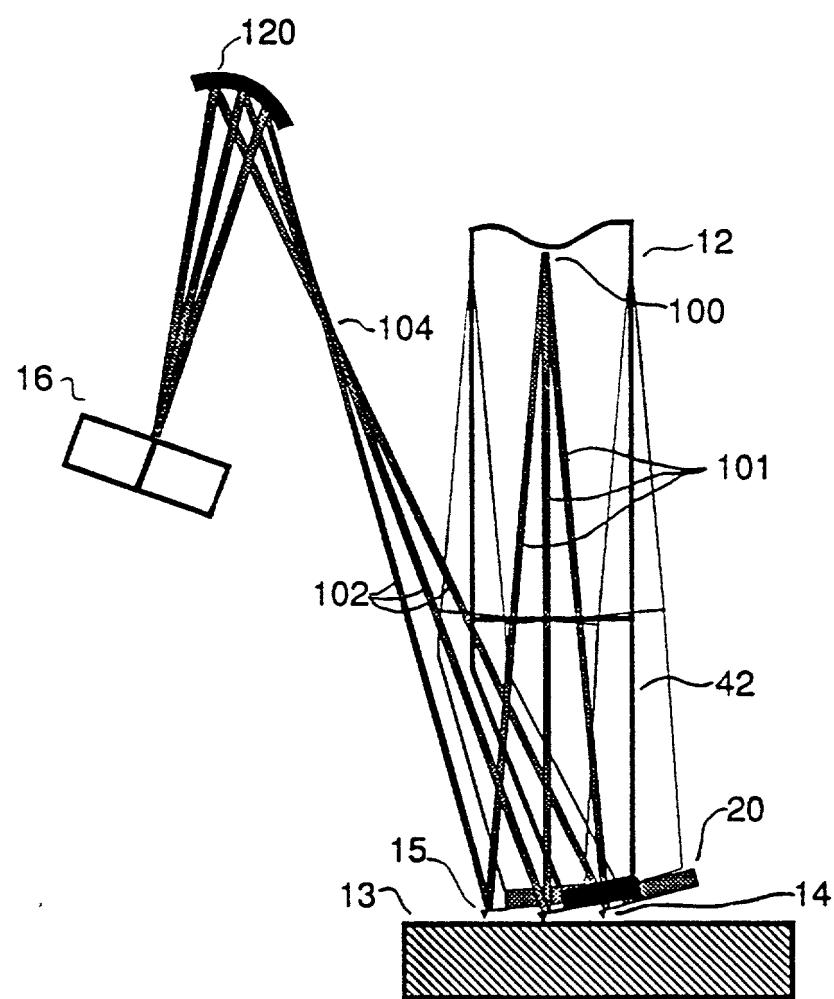


FIG. 13

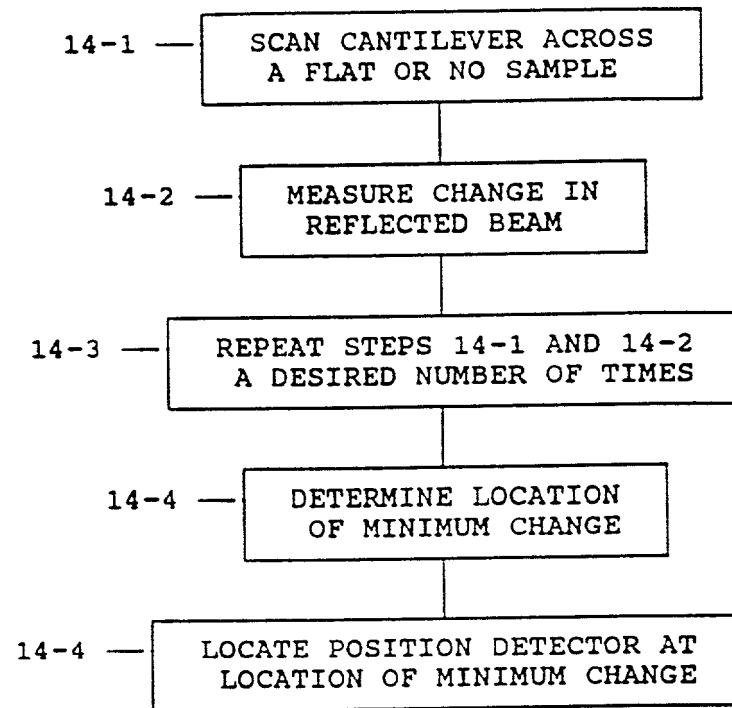


FIG. 14

Declaration, Power Of Attorney and Petition

Page 1 of X4

WE (I) the undersigned inventor(s), hereby declare(s) that:

My residence, post office address and citizenship are as stated below next to my name,

We (I) believe that we are (I am) the original, first, and joint (sole) inventor(s) of the subject matter which is claimed and for which a patent is sought on the invention entitled

ATOMIC FORCE MICROSCOPE AND METHOD OF OPERATING AN ATOMIC FORCE MICROSCOPE

the specification of which

is attached hereto.

was filed on AUGUST 17, 1993 as

Application Serial No. _____

and amended on _____

was filed as PCT international application

Number _____

on _____,

and was amended under PCT Article 19

on _____ (if applicable).

We (I) hereby state that we (I) have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

We (I) acknowledge the duty to disclose information known to be material to the patentability of this application as defined in Section 1.56 of Title 37 Code of Federal Regulations.

We (I) hereby claim foreign priority benefits under Section 119 of Title 35 United States Code, of any foreign application(s) for patent or inventor's certificate listed below and have also identified below any foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed:

Application No.	Country	Day/Month/Year	Priority Claimed
_____	_____	_____	<input type="checkbox"/> Yes <input type="checkbox"/> No
_____	_____	_____	<input type="checkbox"/> Yes <input type="checkbox"/> No
_____	_____	_____	<input type="checkbox"/> Yes <input type="checkbox"/> No
_____	_____	_____	<input type="checkbox"/> Yes <input type="checkbox"/> No

We (I) hereby claim the benefit under Section 120 of Title 35 United States Code, of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Section 112 of Title 35 United States Code, We (I) acknowledge the duty to disclose material information as defined in Section 1.56(a) of Title 37 Code of Federal Regulations, which occurred between the filing date of the prior application and the national or PCT international filing date of this application:

Application Serial No.	Filing Date	Status (pending, patented, abandoned)
_____	_____	_____
_____	_____	_____
_____	_____	_____

And we (I) hereby appoint: Norman F. Oblon, Registration Number 24,618; Marvin J. Spivak, Registration Number 24,913; C. Irvin McClelland, Registration Number 21,124; Gregory J. Maier, Registration Number 25,599; Arthur I. Neustadt, Registration Number 24,854; Robert C. Miller, Registration Number 25,357; Richard D. Kelly, Registration Number 27,757; James D. Hamilton, Registration Number 28,421; Eckhard H. Kuesters, Registration Number 28,870; Robert T. Pous, Registration Number 29,099; Charles L. Gholz, Registration Number 26,395; Vincent J. Sunderdick, Registration Number 29,004; William E. Beaumont, Registration Number 30,996; Steven B. Kelber, Registration Number 30,073; Stuart D. Dwork, Registration Number 31,103; Robert F. Gnuse, Registration Number 27,295; Jean-Paul Lavalleye, Registration Number 31,451; William B. Walker, Registration Number 22,498; Timothy R. Schwartz, Registration Number 32,171; Richard H. Stern, Registration Number 20,380; Stephen G. Baxter, Registration Number 32,884; and John H.O. Clarke, Registration Number 17,373; our (my) attorneys, with full powers of substitution and revocation, to prosecute this application and to transact all business in the Patent Office connected therewith; and we (I) hereby request that all correspondence regarding this application be sent to the firm of OBLON, SPIVAK, McCLELLAND, MAIER & NEUSTADT, P.C., whose Post Office Address is: Fourth Floor, 1755 Jefferson Davis Highway, Arlington, Virginia 22202.

We (I) declare that all statements made herein of our (my) own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Craig B. Prater
NAME OF FIRST ~~XXXX~~ INVENTOR

Craig Prater

Signature of Inventor

10/5/93
Date

Residence: 5530 Pembroke
Santa Barbara, CA 93111

Citizen of: USA

Post Office Address: C/O DIGITAL INSTRUMENTS, INC.
520 E. Montecito Street
Santa Barbara, CA 93103

JAMES MASSIE
NAME OF SECOND JOINT INVENTOR

James R. Massie
Signature of Inventor

10/5/93
Date

DAVID A. GRIGG
NAME OF THIRD JOINT INVENTOR

D. A. Grigg
Signature of Inventor

Oct 5 1993
Date

VIRGIL B. ELINGS
NAME OF FOURTH JOINT INVENTOR

Virgil B. Elings
Signature of Inventor

Oct 5 1993
Date

PAUL K. HANSMA
NAME OF FIFTH JOINT INVENTOR

Paul Hansma
Signature of Inventor

Oct 7, 1993
Date

Residence: 473 Mountain Drive
Santa Barbara, CA 93103

Citizen of: USA
Post Office Address: c/o DIGITAL INSTRUMENTS, INC.
520 Montecito Street
Santa Barbara, CA 93103

Residence: 1217 Stonecreek Rd.
Unit E
Santa Barbara, CA 93105

Citizen of: USA
Post Office Address: c/o DIGITAL INSTRUMENTS, INC.
520 Montecito Street
Santa Barbara, CA 93103

Residence: 1155 Via Tranquila
Santa Barbara, CA 93110

Citizen of: USA
Post Office Address: c/o DIGITAL INSTRUMENTS, INC.
520 Montecito Street
Santa Barbara, CA 93103

Residence: 6891 Triigo Road
Santa Barbara, CA 93117

Citizen of: USA
Post Office Address: c/o UNIVERSITY OF CALIFORNIA OF SANTA BARBARA, Department of Physics, Santa Barbara, CA 93106

08/107,017
B-17-93

ASSIGNMENT

U.C. Case No. 92-176-1

For good and valuable consideration, the receipt of which is hereby acknowledged, ASSIGNOR(S),

1. Paul K. HANSMA

2. Barney DRAKE

hereby sells, assigns and transfers to ASSIGNEE, The Regents of the University of California, a California Corporation, having its statewide administrative offices located 300 Lakeside Drive, 22nd Fl., Oakland, CA 94612-3550, and the successors, assigns and legal representatives of the ASSIGNEE all of its right, title and interest for the United States and its territorial possessions and in all foreign countries in and to, any and all improvements which are disclosed in the invention entitled:

TITLE ATOMIC FORCE MICROSCOPE AND METHOD OF OPERATING AN ATOMIC FORCE MICROSCOPE

and which is found in

(a) U.S. patent application executed on _____, entitled as above and listing the above named persons as inventors

(b) U.S. application serial no. 107,017, filed on August 17, 1993

(c) U.S. Patent No.: _____, issued _____

and any legal equivalent thereof in a foreign country, including the right to claim priority and, in and to, all Letters Patent to be obtained for said invention by the above application or any continuation, division, continuation-in-part, extension or substitute thereof, and any reissue, reexamination or extension of said Letters Patent and all rights under all International Conventions for the Protection of Industrial Property;

ASSIGNOR(S) hereby covenants that no assignment, sale, agreement or encumbrance has been or will be made or entered into which would conflict with this assignment;

ASSIGNOR(S) further covenants that ASSIGNEE will, upon its request, be provided promptly with all pertinent facts and documents relating to said invention and said Letters Patent and legal equivalents as may be known and accessible to ASSIGNOR and will testify as to the same in any interference, litigation, or proceeding relating thereto and will promptly execute and deliver to ASSIGNEE or its legal representative any and all papers, instruments or affidavits required to apply for, obtain, maintain, issue or enforce said application, said invention and said Letters Patent and said equivalents thereof which may be necessary or desirable to carry out the purposes thereof. An attorney of record is authorized and requested by the execution of this assignment to insert into this assignment the filing date and serial number of said application when officially known.

AND the ASSIGNOR(S) requests the Commissioner of Patents and Trademarks to issue said Letters Patent of the United States and any reissue or extension thereof to the ASSIGNEE, The Regents of the University of California.

executed this

✓ 29 day of March, 1994

✓ 31 day of March, 1994

Signature of Inventor(s)

Paul K. HANSMA

Paul K. HANSMA

Barney DRAKE

Barney DRAKE

PPR-4 95

U. S. PATENT & TRADEMARK
OFFICE

REF 1425 FILE 311

BARNEY DRAKE
NAME OF ~~SECOND~~ JOINT INVENTOR
SIXTH

Barney Drake
Signature of Inventor

10/8/93
Date

~~NAME OF ~~SECOND~~ JOINT INVENTOR~~

~~Signature of Inventor~~

~~Date~~

~~NAME OF ~~FOURTH~~ JOINT INVENTOR~~

~~Signature of Inventor~~

~~Date~~

~~NAME OF ~~FIFTH~~ JOINT INVENTOR~~

~~Signature of Inventor~~

~~Date~~

Residence: 545 North Patterson

931085
Santa Barbara, CA 93111

Citizen of: USA

Post Office Address: c/o UNIVERSITY OF CALI-
FORNIA OF SANTA BARBARA, Department of
Physics, Santa Barbara, CA 93106

Residence: _____

Citizen of: _____

Post Office Address: _____

Residence: _____

Citizen of: _____

Post Office Address: _____

Residence: _____

Citizen of: _____

Post Office Address: _____

COPY

Assignment Of Application

Page 1 of 2

WHEREAS, I (WE) Craig B. PRATER

5530 Pembroke
Santa Barbara, California 93111

INSERT NAMES
AND RESIDENCE
ADDRESSES OF
THE INVENTORS:

James MASSIE

473 Mountain Drive
Santa Barbara, California 93103

David A. GRIGG

1217 Stonecreek Road, Unit E
Santa Barbara, California 93105

Virgil B. ELINGS

4664 Via Clarice
Santa Barbara, California 93110

, respectively,

INSERT TITLE
OF INVENTION:

have invented certain new and useful improvements in: ATOMIC FORCE MICROSCOPE AND

METHOD OF OPERATING AN ATOMIC FORCE MICROSCOPE

INSERT DATE IN-
VENTORS SIGNED
DECLARATION:

for which an application for Letters Patent was executed on Oct. 5, 7, and 8, 1993, respectively

(Application No. 08/107,017, filed August 17, 1993), and

INSERT NAME
AND ADDRESS OF
COMPANY OR
OTHER ASSIGNEE:

WHEREAS, DIGITAL INSTRUMENTS, INC.

(hereinafter referred to as "ASSIGNEE") having a place of business at:

520 E. Montecito Street, Santa Barbara, CA 93103

is desirous of acquiring the entire right, title and interest in and to said invention and in and to any Letters Patent that may be granted therefore in the United States and its territorial possessions and in any and all foreign countries:

NOW, THEREFORE, in consideration of the sum of FIVE DOLLARS (\$5.00), the receipt whereof is hereby acknowledged, and for other good and valuable consideration, I (WE), by these presents do sell, assign and transfer unto said ASSIGNEE, the full and exclusive right to the said invention in the United States and its territorial possessions and in all foreign countries and the entire right, title and interest in and to any and all Letters Patent which may be granted therefor in the United States and its territorial possessions and in any and all foreign countries and in and to any and all divisions, reissues, continuations, substitutions and renewals thereof.

I (WE) hereby authorize and request the Patent Office Officials in the United States and its territorial possessions and any and all foreign countries to issue any and all of said Letters Patent, when granted, to said ASSIGNEE as the assignee of my (our) entire right, title and interest in and to the same, for the sole use and behoof of said ASSIGNEE, its (his) successors and assigns, to the full end of the term for which said Letters Patent may be granted, as fully and entirely as the same would have been held by me (us) had this Assignment and sale not been made.

Further, I (WE) agree that I (WE) will communicate to said ASSIGNEE or its (his) representatives any facts known to me (us) respecting said invention, and testify in any legal proceeding, sign all lawful papers, execute all divisional, continuation, substitute, renewal and reissue applications, execute all necessary assignment papers to cause any and all of said Letter Patent to be issued to said ASSIGNEE, make all rightful oaths, and, generally do everything possible to aid said ASSIGNEE, its (his) successors and assigns, to obtain and enforce proper protection for said invention in the United States and its territorial possessions and in any and all foreign countries.

The undersigned hereby grant(s) the firm of Oblon, Spivak, McClelland, Maier & Neustadt, P.C. of Fourth Floor, 1755 Jefferson Davis Highway, Arlington, Virginia 22202 the power to insert on this assignment any further identification, including the application number and filing date, which may be necessary or desirable in order to comply with the rules of the United States Patent and Trademark Office for recordation of this document.

✓ Date: _____
(Signature of Inventor)
Craig B. PRATER

✓ Date: _____
(Signature of Inventor)
James MASSIE

✓ Date: _____
(Signature of Inventor)
David A. GRIGG

Date: _____
(Signature of Inventor)
Virgil B. ELINGS

Date: _____
(Signature of Inventor)

OBLON, SPIVAK, McCLELLAND, MAIER & NEUSTADT, P.C.
ATTORNEYS AT LAW
FOURTH FLOOR
1755 JEFFERSON DAVIS HIGHWAY
ARLINGTON, VIRGINIA 22202

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Application of:) **Attorney Docket: D9310**
CRAIG B. PRATER ET AL.)
Serial No.: 08/679,332)
Filed: JULY 11, 1996)
Group Art Unit: 2212)
Examiner: LARKIN)
For: SCANNING STYLUS ATOMIC FORCE)
MICROSCOPE WITH CANTILEVER)
TRACKING AND OPTICAL ACCESS)

I HEREBY CERTIFY THAT THIS CORRESPONDENCE IS BEING
DEPOSITED WITH THE UNITED STATES POSTAL SERVICE AS
FIRST CLASS MAIL IN AN ENVELOPE ADDRESSED TO
COMMISSIONER OF PATENT AND TRADEMARKS
WASHINGTON, D.C. 20231, ON May 27, 1997

R. Taylor 5/27/97
DATE

SUBMISSION OF POWER OF ATTORNEY

Honorable Commissioner of Patents
and Trademarks
U. S. PATENT & TRADEMARK OFFICE
Washington, D.C. 20231

Sir:

Enclosed is the Power of Attorney signed by the president of the
owner/assignee of the above-identified patent application. Since the undersigned
has been appointed by the owner/assignee to be its attorney of record for all
matters pertaining to the above-identified application before the PTO, the
undersigned requests that the attached Power of Attorney be made part of the
record of this patent application.

Serial No. 08/679,332
Applicants: C. PRATER et al.

Page 2

The Commissioner is authorized to charge Deposit Account No. 02-3823 for any fee or cost incurred by submission of this letter and/or the attached Power of Attorney, or to credit any overpayment to said Deposit Account. A copy of this letter is attached hereto for this purpose.

Respectfully submitted,



May 27, 1997

Patrick F. Bright
Reg. No. 24,318
BRIGHT & LORIG, P. C.
633 West Fifth Street, #3330
Los Angeles, CA 90071
(213) 627-7774

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Application of:) **Attorney Docket: D9310**
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DEPOSITED WITH THE UNITED STATES POSTAL SERVICE AS
FIRST CLASS MAIL IN AN ENVELOPE ADDRESSED TO
COMMISSIONER OF PATENT AND TRADEMARKS
WASHINGTON, D.C. 20231, ON May 27, 1997
R. Taylor 5/27/97
DATE

POWER OF ATTORNEY

Honorable Commissioner of Patents
and Trademarks
U. S. PATENT & TRADEMARK OFFICE
Washington, D.C. 20231

Sir:

As the president of the owner/assignee for the above-identified application ,

I hereby revoke all powers of attorney previously given and hereby appoint the
following attorneys to transact all business in the U. S. Patent & Trademark Office
connected with this application:

PATRICK F. BRIGHT, Reg. No. 24,318

U. S. Patent No. 5,808,974 Appln. No. 08/679,332
Patentees: ~~ELINGS~~ et al. Applicants: C. PRATER ET AL.

Page 2

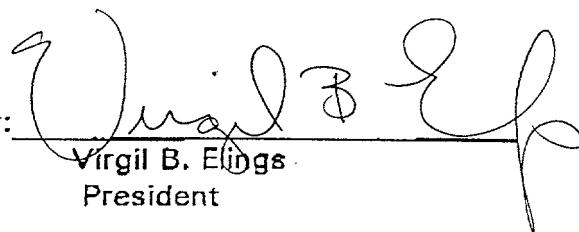
All correspondence relating to this application is to be addressed to: Patrick F. Bright, Esq., BRIGHT & LORIG, P. C., 633 West Fifth Street, Suite 3330, Los Angeles, CA 90071.

Respectfully submitted,

DIGITAL INSTRUMENTS, INC.,
Assignee

May 22, 1997

By:


Virgil B. Elings

President